



# Causal Inference for Time Series and Applications to Climate

Urmi Ninad | TU Berlin | Berlin Applied Causal Graphs Workshop (23 April 2024)



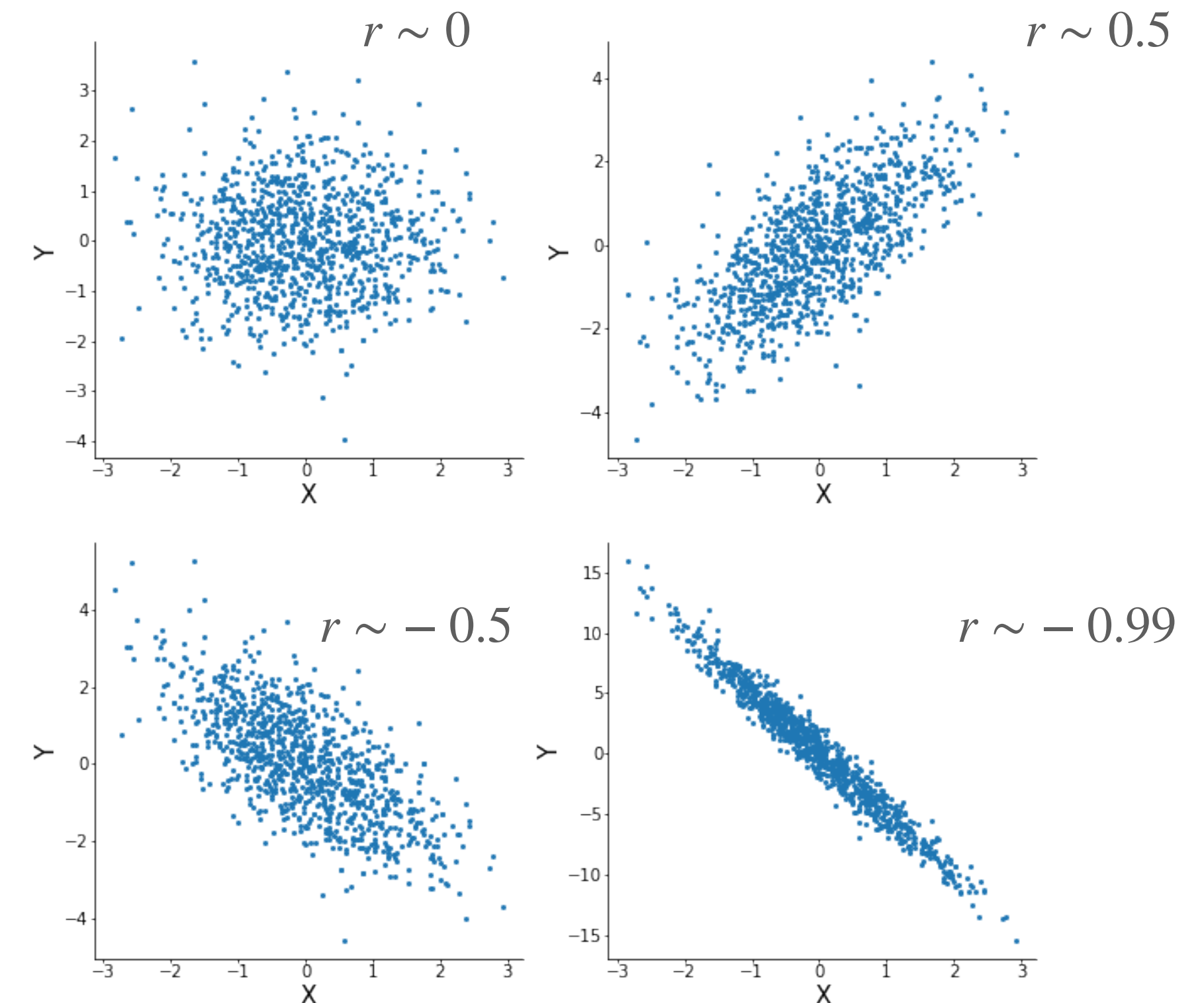


# Correlation in Statistical Inference

“A Causality-free Science”



- Pearson correlation coefficient  $r$  measures the correlation between two random variables  $X$  and  $Y$  (right)
- Karl Pearson said “Science in no case can demonstrate any inherent necessity in a sequence, nor prove with absolute certainty that it must be repeated”<sup>1</sup>
- “.. the idea of causation is extracted by conceptual processes from phenomena, it is neither a logical necessity, nor an actual experience. We can merely classify things as like; we cannot reproduce sameness, but *we can only measure how relatively like follows relatively like*. The wider view of the universe sees all phenomena as correlated, but not causally related.”<sup>1</sup>



1: Pearson, “Grammar of Science”, 1892





# The Need for a Causal Framework

## Formalising causal queries

- **Understanding:** *Why* do I observe what I observe?  
Eg.: Why can I, a human, reliably distinguish images of cats and dogs?
- **Attribution:** Did a certain event take place *due to* a certain action in the past? Would it have been different if a different action been chosen?  
Eg: Are extreme climatic events becoming more frequent because of anthropogenic contributions?
- **Decision making:** What should I do to achieve a *certain goal*?  
Eg: How can I enhance the cognitive function of a population?
- **Robust prediction and forecasting:** Given I observe X, *what* is Y?  
Predictive systems consistent with the underlying causal structures may show a better out-of-distribution generalisation.  
Eg: Will it rain tomorrow?



Figure sources:  
 1. Getty  
 2. CNN, Ahr Valley 2021 floods  
 3. Tiny-Giant.net  
 4. Apple weather app





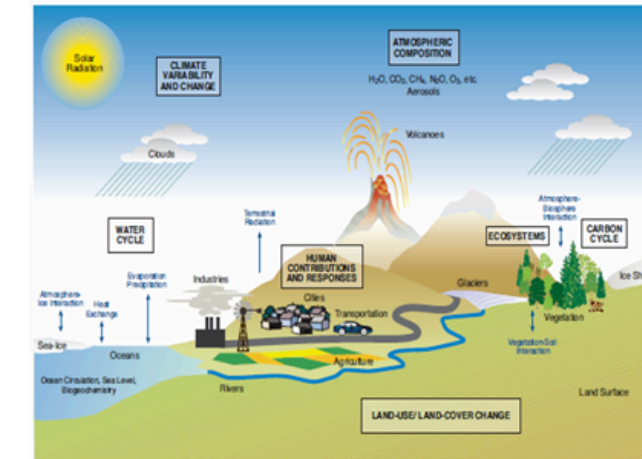
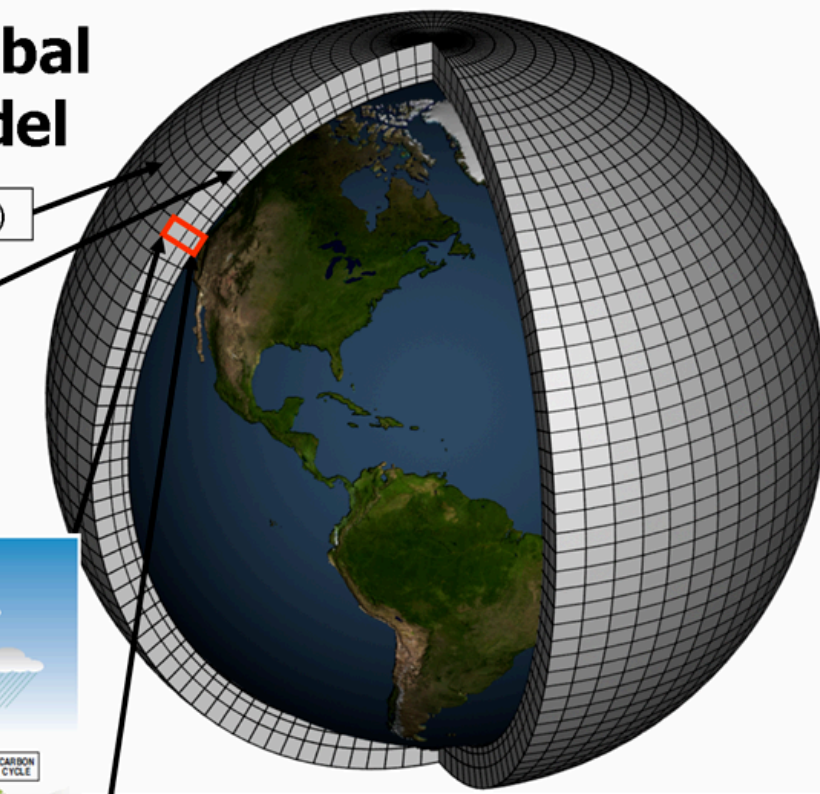
# do-experiments are Hard to Do



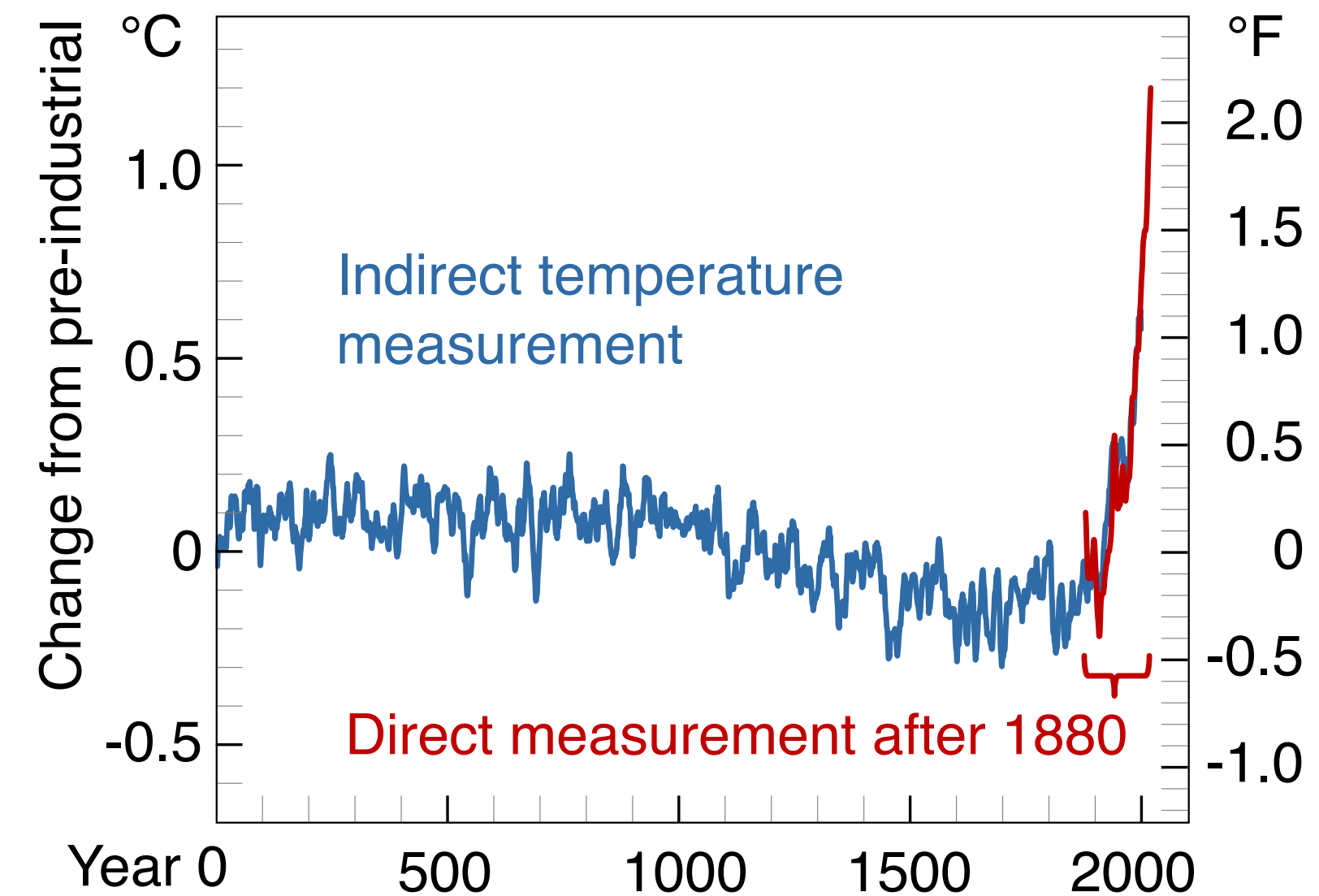
- Interventions can be unethical
- Interventions can be impossible or highly impractical
- Interventions can be expensive

## Schematic for Global Atmospheric Model

Horizontal Grid (Latitude-Longitude)  
Vertical Grid (Height or Pressure)



## Global temperature in the Common Era



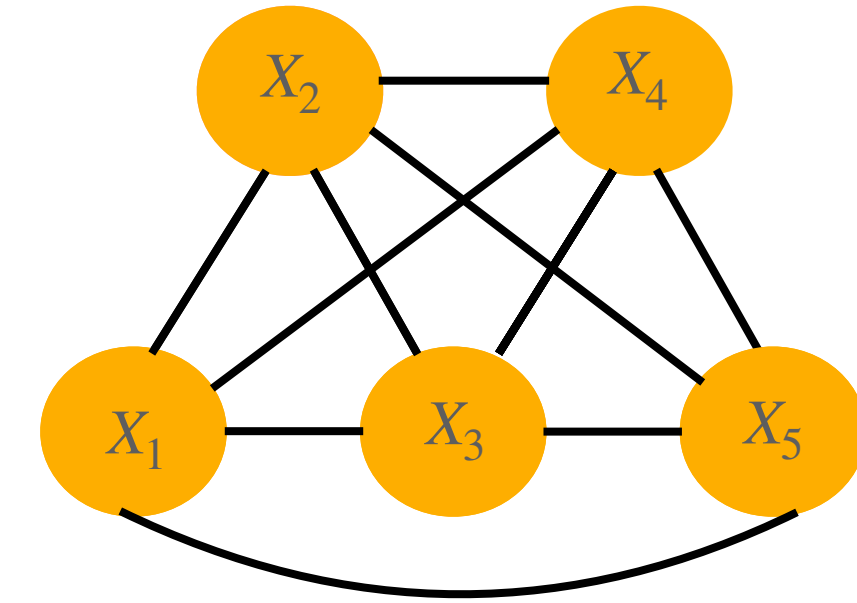






# Causal Structure Learning

Query: What Can we Do without Prior Assumptions?



- Given a dataset of samples for five random variables, what can we say about their causal relationships?
- We are supplied with conditional independence tests:

$$X_1 \perp X_3 | X_2, X_1 \perp X_4, X_1 \perp X_5$$

$$X_2 \perp X_4, X_2 \perp X_5$$

$$X_3 \perp X_5 | X_4$$

- What can we say about the causal graph between these variables?

$X_1$	$X_2$	$X_3$	$X_4$	$X_5$
0.7	0.6	1.33	2.4	0.01
0.5	0.56	0.98	2.2	...
0.75	0.5	1.56	...	...
0.6	...	...	...	...
0.56	...	...	...	...
0.53	...	...	...	...
0.69	...	...	...	...
0.5	...	...	...	...
0.7	...	...	...	...
...	...	...	...	...

Answer: **Nothing** :/

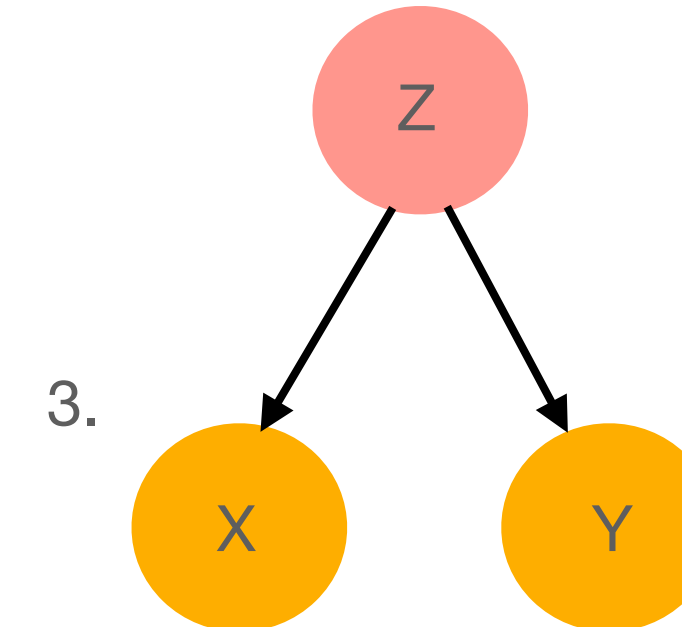
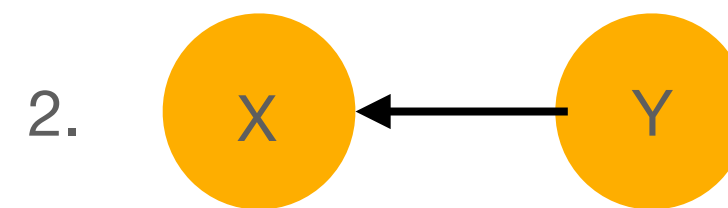
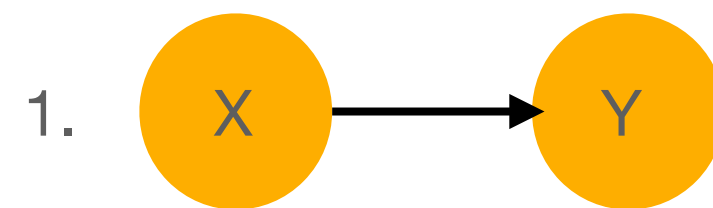


# Interlude: Reichenbach's Common Cause Principle<sup>1</sup>

An intuition to formalise the connection between causality and statistical dependence

If two random variables  $X$  and  $Y$  are statistically dependent ( $X \not\perp Y$ ), then :

1.  $X$  is (possibly indirectly) causing  $Y$  , or
2.  $Y$  is (possibly indirectly) causing  $X$ , or
3. there is a (possibly unobserved) common cause  $Z$  that (possibly indirectly) causes both  $X$  and  $Y$



Generally: Statistical dependence  $\implies$  Causal 'connectedness': **Causal Markov Condition**

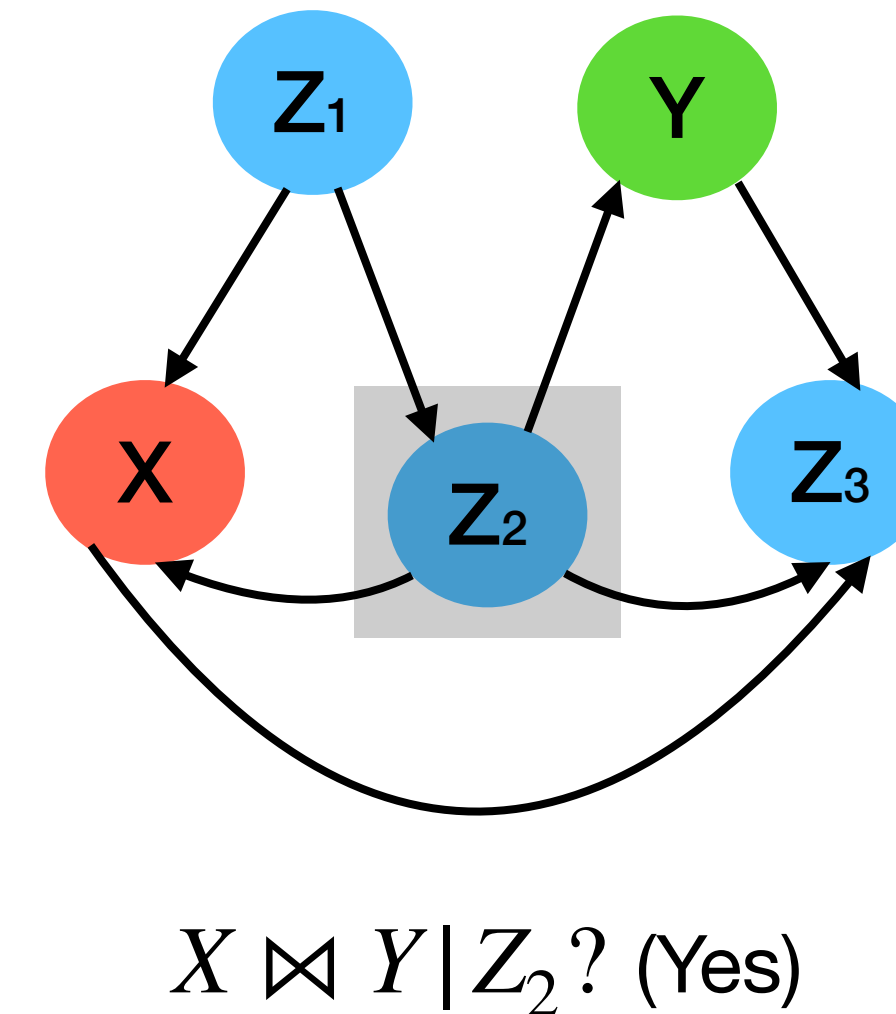
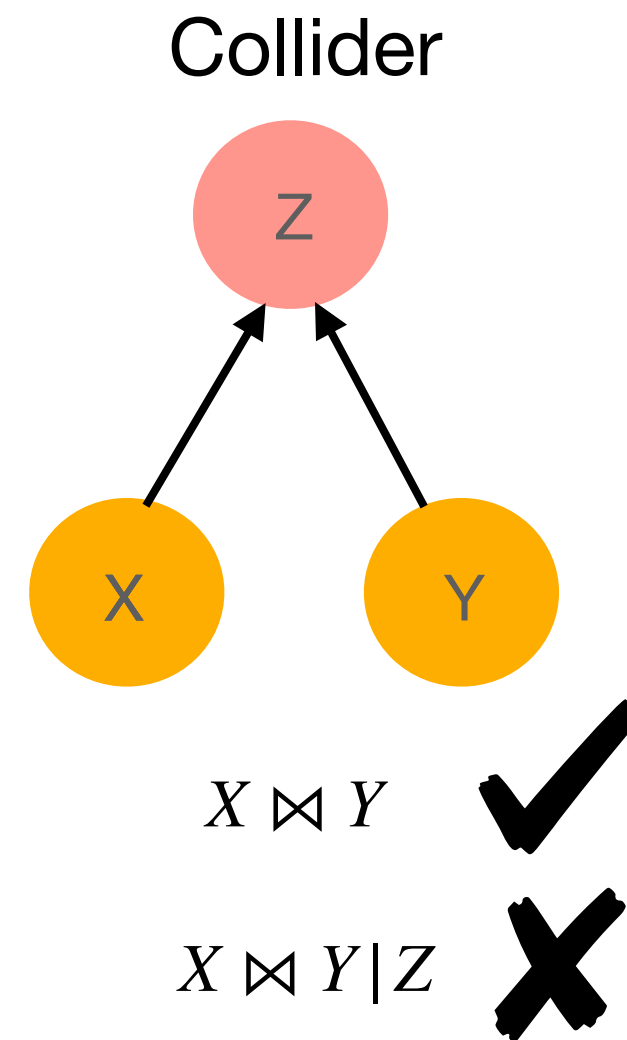
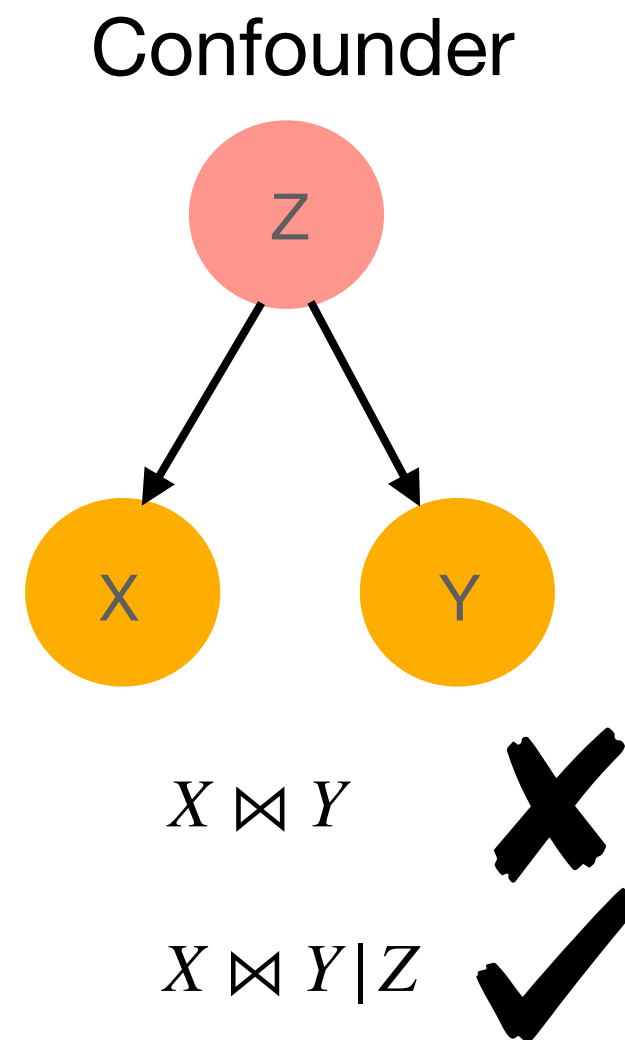
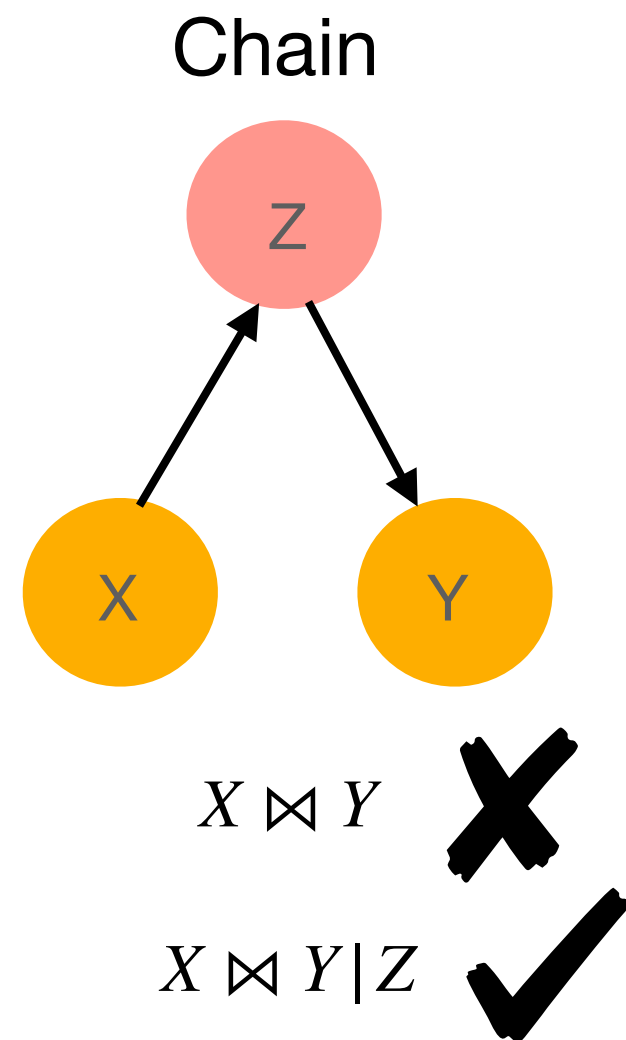




# d-separation and Causal Markov Condition

A graphical criterion to aid causal inference

- A vertex  $X$  in a graph is said to be d-separate ( $\perp\!\!\!\perp$ ) from another vertex  $Y$  given a set of vertices  $S$ , when a set of conditions concerning all paths from  $X$  to  $Y$  are satisfied.



- Causal Markov Condition:**  $X \perp\!\!\!\perp Y | Z \Rightarrow X \perp\!\!\!\perp Y | Z$  (Causal graph is Markov relative to  $P_{X,Y,\dots}$ )
- ‘The underlying causal graphical structure leaves certain (conditional) independencies as imprints in the observational distribution.’





# Causal Faithfulness Assumption

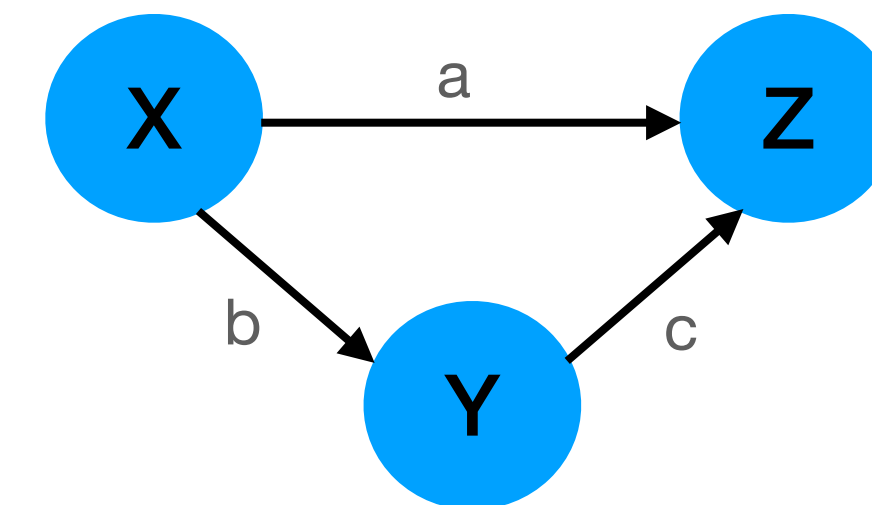
The other side of the coin

- If all the (conditional) independencies implied by the Markov condition are true, and no more, then causal faithfulness is said to hold.
- Causal faithfulness Assumption :  $X \perp\!\!\!\perp Y | Z \Rightarrow X \not\propto Y | Z$
- Both the causal Markov and causal faithfulness properties state a relationship between a causal graph and probability distribution over the same set of variables.

$X := \eta_X$   
 $Y := b \cdot X + \eta_Y$   
 $Z := a \cdot X + c \cdot Y + \eta_Z$

Here  $\eta_i \sim N(0,1)$  are independent noise terms.

(The ‘:=’ denotes that these are *causal* assignments, and the set of equations together is called a *structural causal model*)



- If  $a = -b \cdot c$ , then causal faithfulness is violated. Therefore, we rule out such fine-tuning of causal influences from different paths when we assume faithfulness.



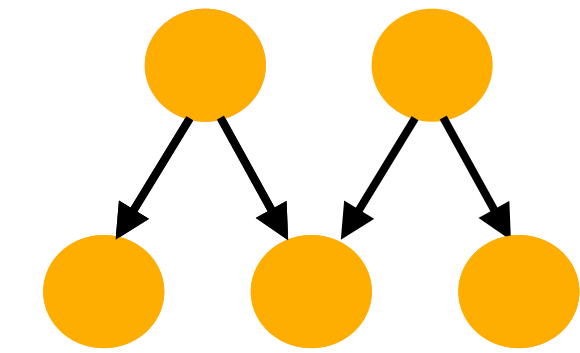


# The PC Algorithm for Causal Graph Discovery



- The PC algorithm<sup>1</sup> has become the standard example for the success of causal (graph) discovery using conditional independence testing.
- It assumes causal Markov property, faithfulness, no cycles and no hidden common causes

Ground Truth  $\mathcal{G}$

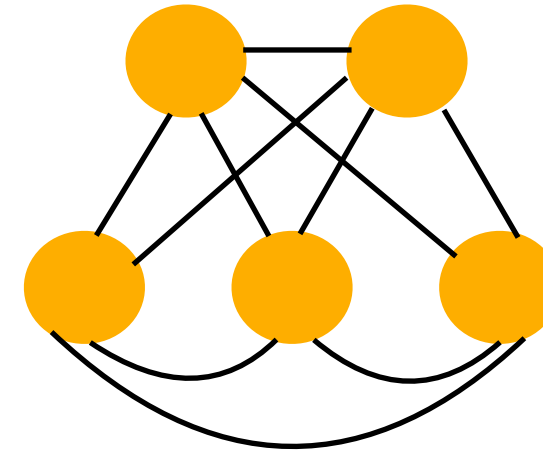


1: Spirtes, Glamour, Scheines, "Causation, Prediction and Search", 2000  
2. Meek, "Complete Orientation Rules for Patterns", '95

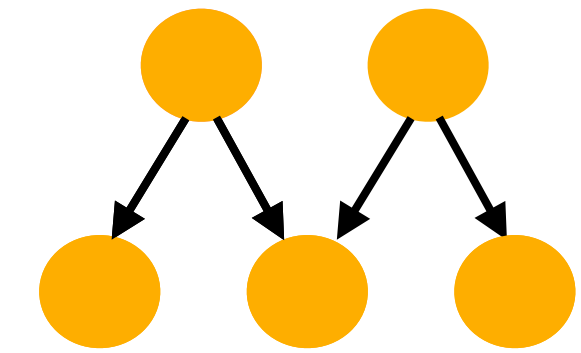


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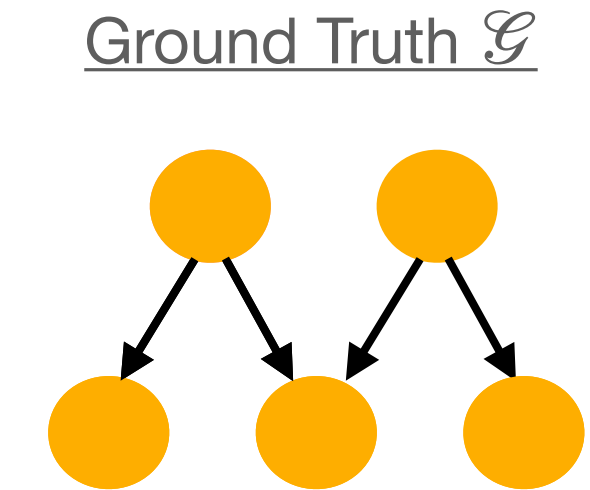
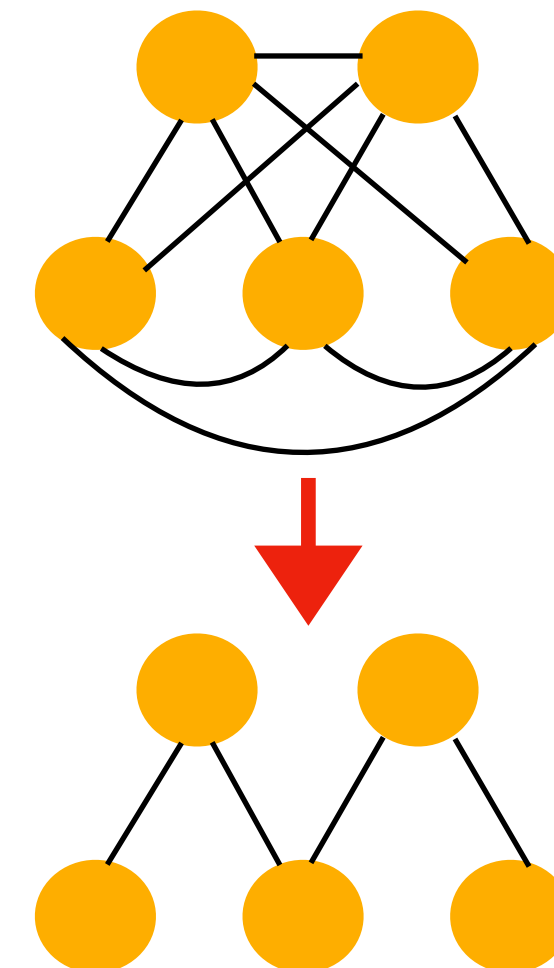


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- To discover a causal graph  $\mathcal{G}$  over variables  $X_1, \dots, X_n$ , start with a **fully-connected undirected graph**  $G$ .
  - Progressively remove edges to get **skeleton** graph:

```

p = 0
For (Xi, Xj) ∈ X:
  For S ⊂ adj(Xi) or S ⊂ adj(Xj) : (adj(X) := adjacencies of X)
    If Xi ⊥ Xj | S and |S| = p: Remove Xi - Xj edge
  p = p + 1
  
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2. Progressively remove edges to get **skeleton** graph:

$$p = 0$$

For  $(X_i, X_j) \in \mathbf{X}$ :

For  $S \subset adj(X_i)$  or  $S \subset adj(X_j)$ : ( $adj(X) :=$  adjacencies of  $X$ )

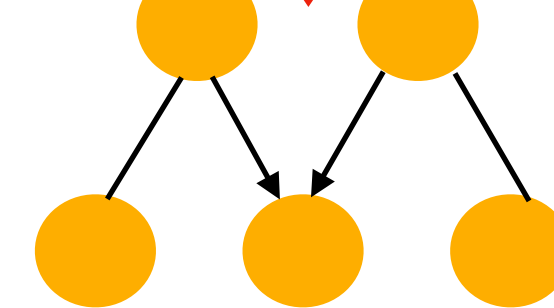
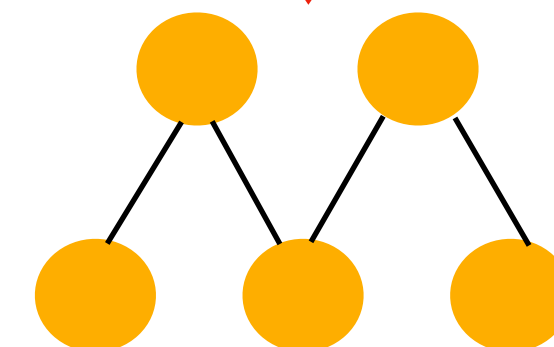
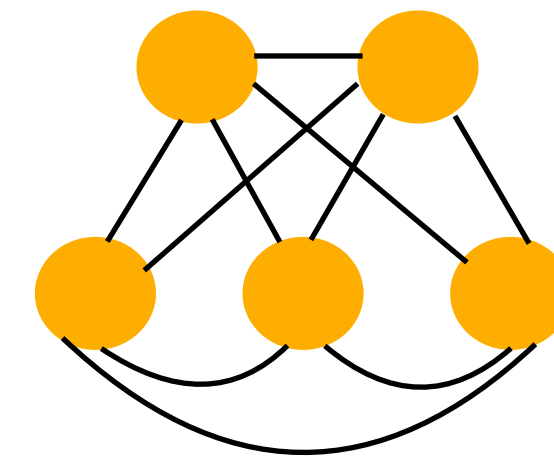
If  $X_i \perp\!\!\!\perp X_j \mid S$  and  $|S| = p$ : Remove  $X_i - X_j$  edge

$$p = p + 1$$

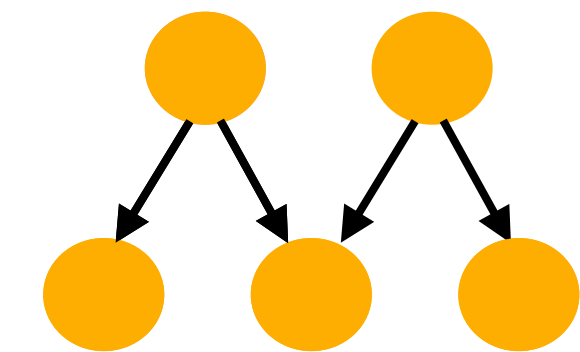
3. Orient **colliders**  $X_i - X_j - X_k \Rightarrow X_i \rightarrow X_j \leftarrow X_k$

When  $X_i \perp\!\!\!\perp X_k \mid S$  and  $X_j \notin S$

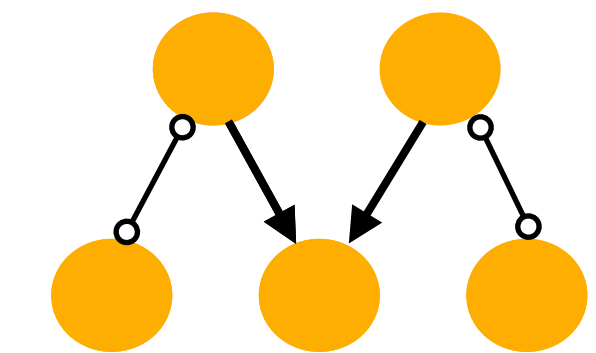
4. Orient as many remaining edges as possible (using **orientation rules**<sup>2</sup>)



Ground Truth  $\mathcal{G}$



PC output



(  $\circ \text{---} \circ = \leftarrow \text{ or } \rightarrow$  )

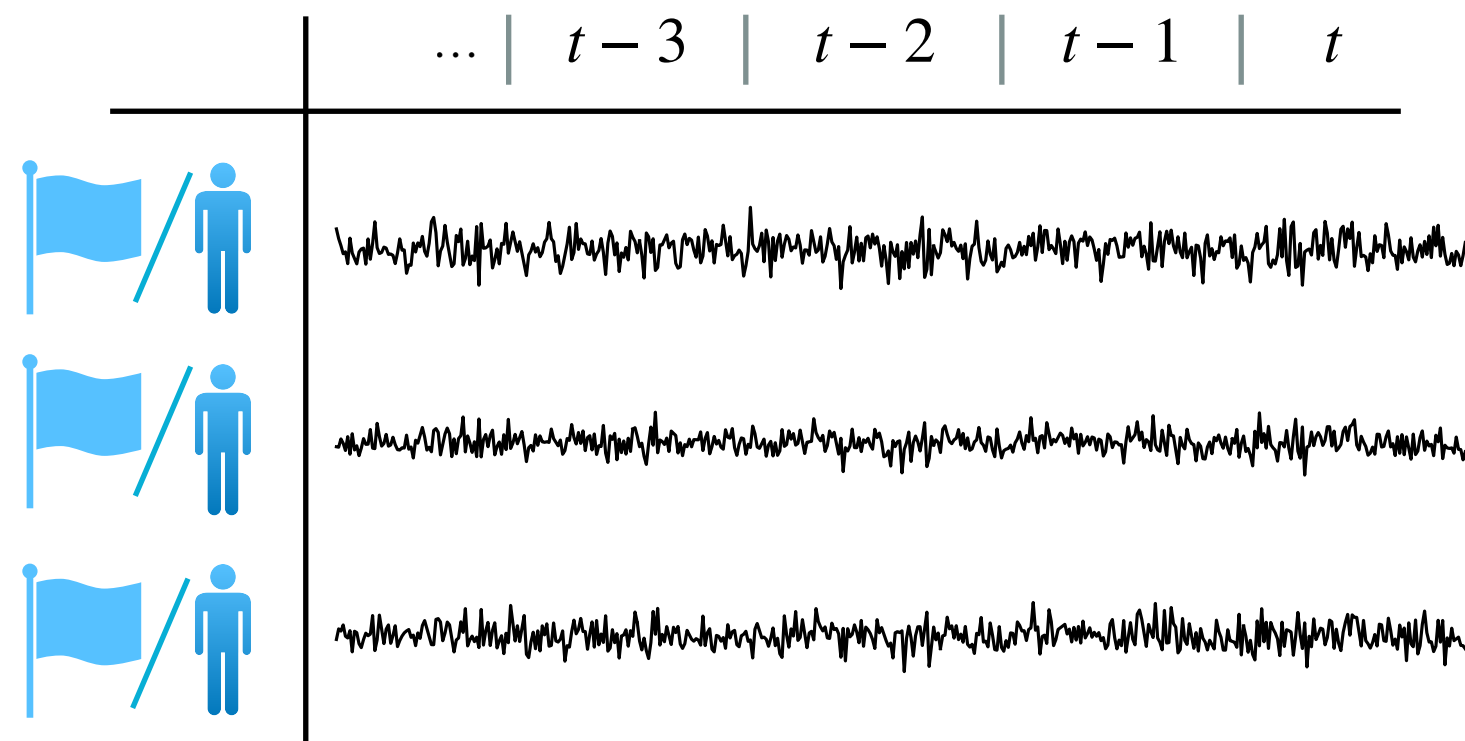


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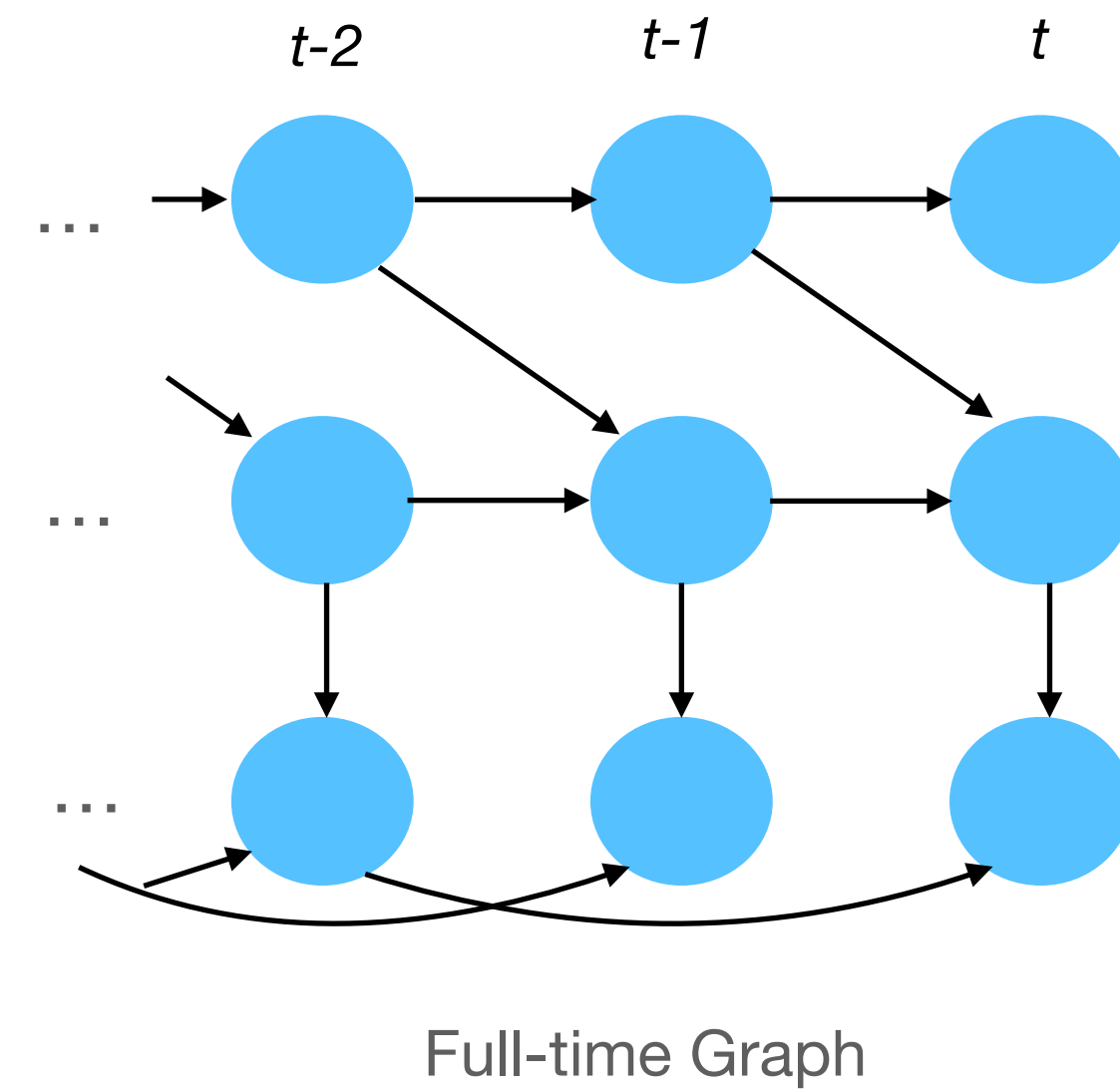
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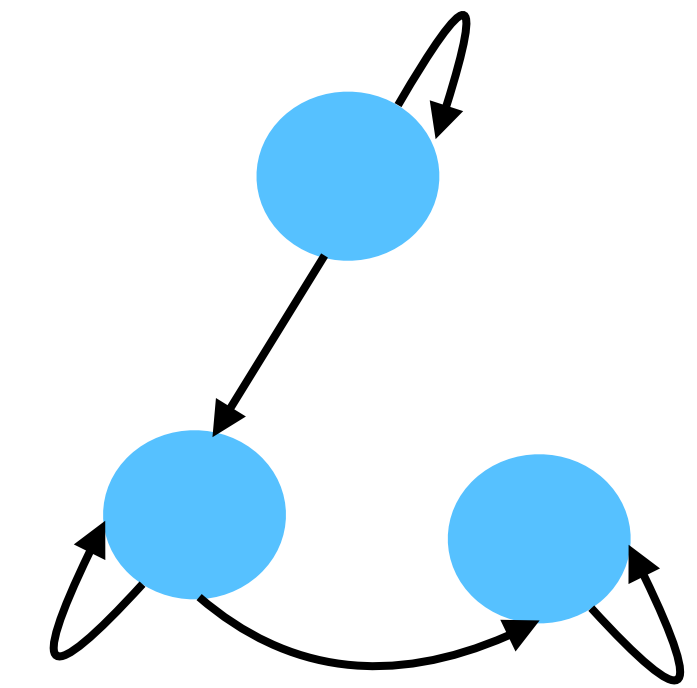
## Possible Target Graphs



- **Full-time Graph** stretches infinitely into the past and the future
- **Summary Graph** is a finite graph that does not retain information about time-lags and time-indices
- **Extended Summary Graph** goes midway between the former two: it is a finite graph which distinguishes between lagged and contemporaneous links

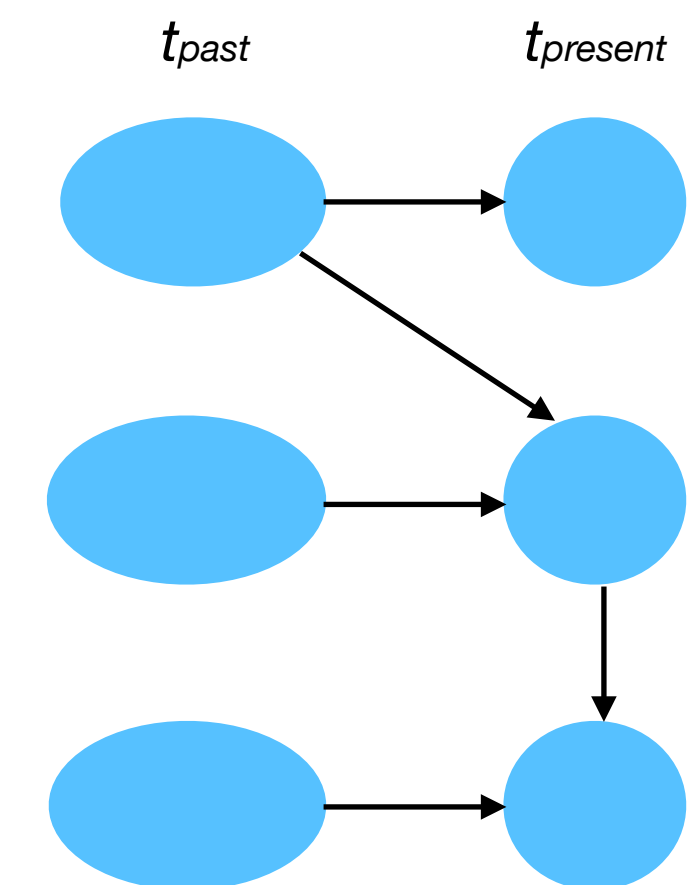


Full-time Graph



Summary Graph

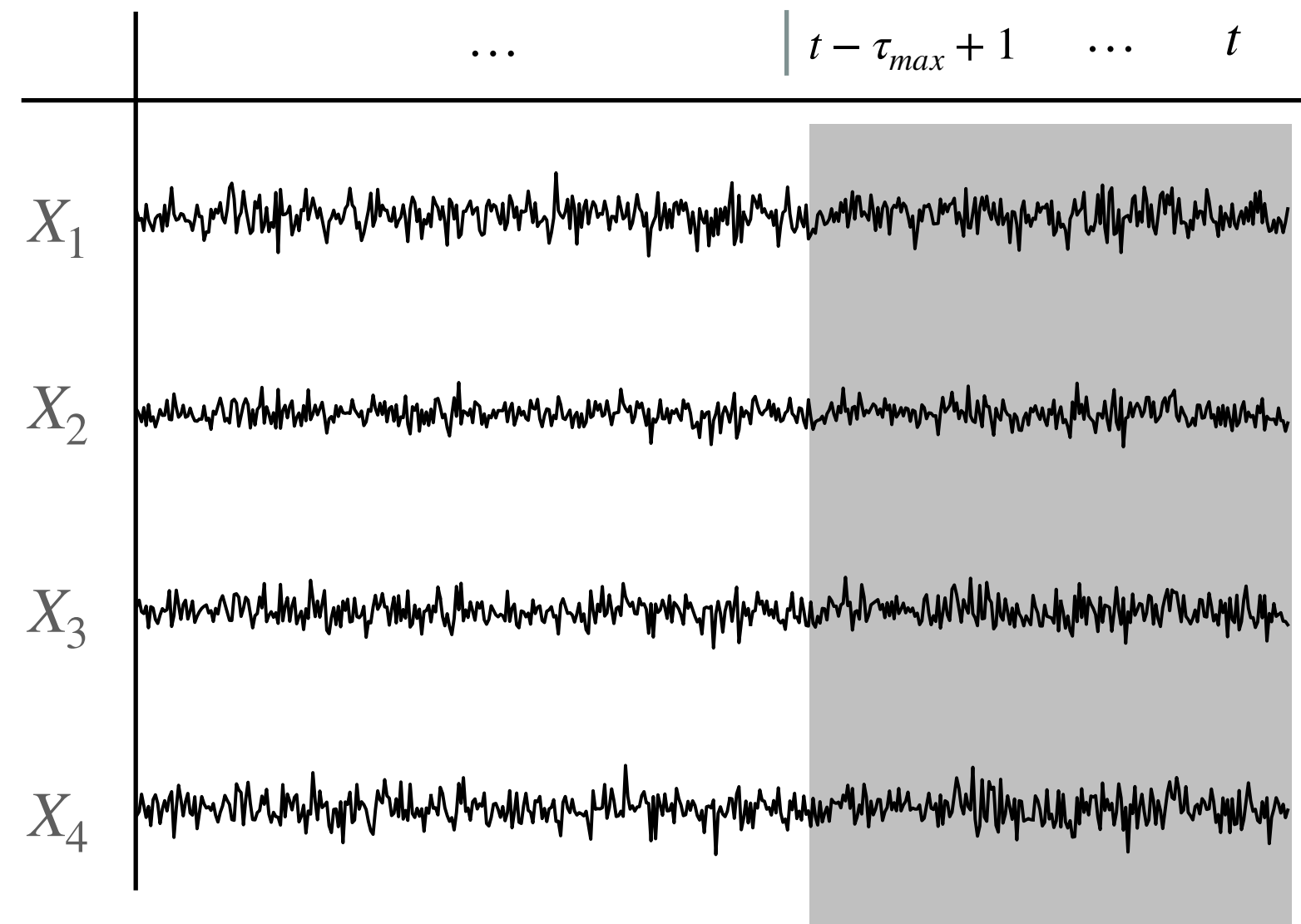
Extended Summary Graph



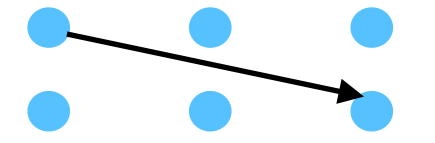


# Causal Inference for Time Series

Basic tenets of time-series causal graph discovery

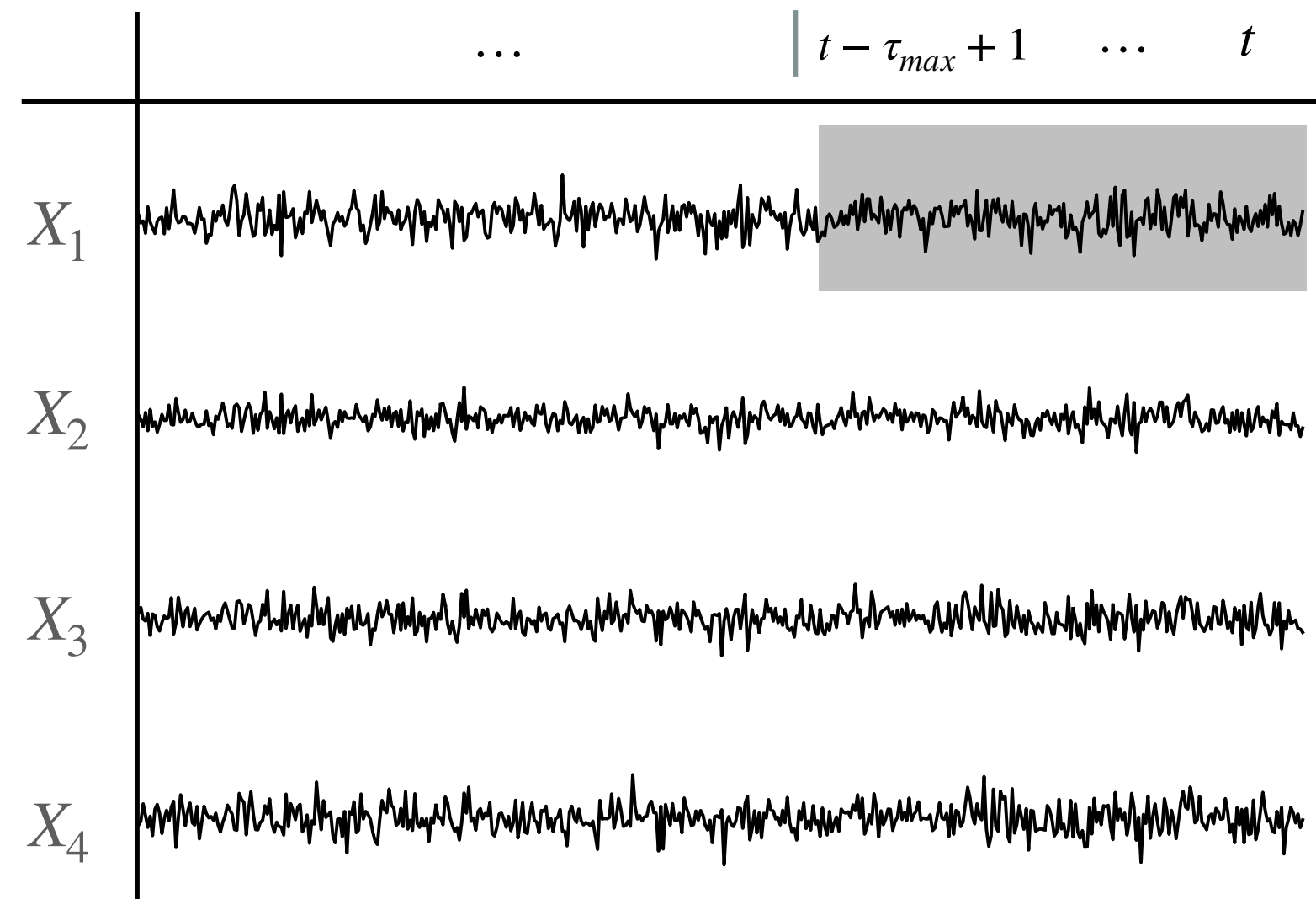


- Start with maximum time lag  $\tau_{max}$ , provided by domain expert or intuition, eg.  $\tau_{max} = 3$ .

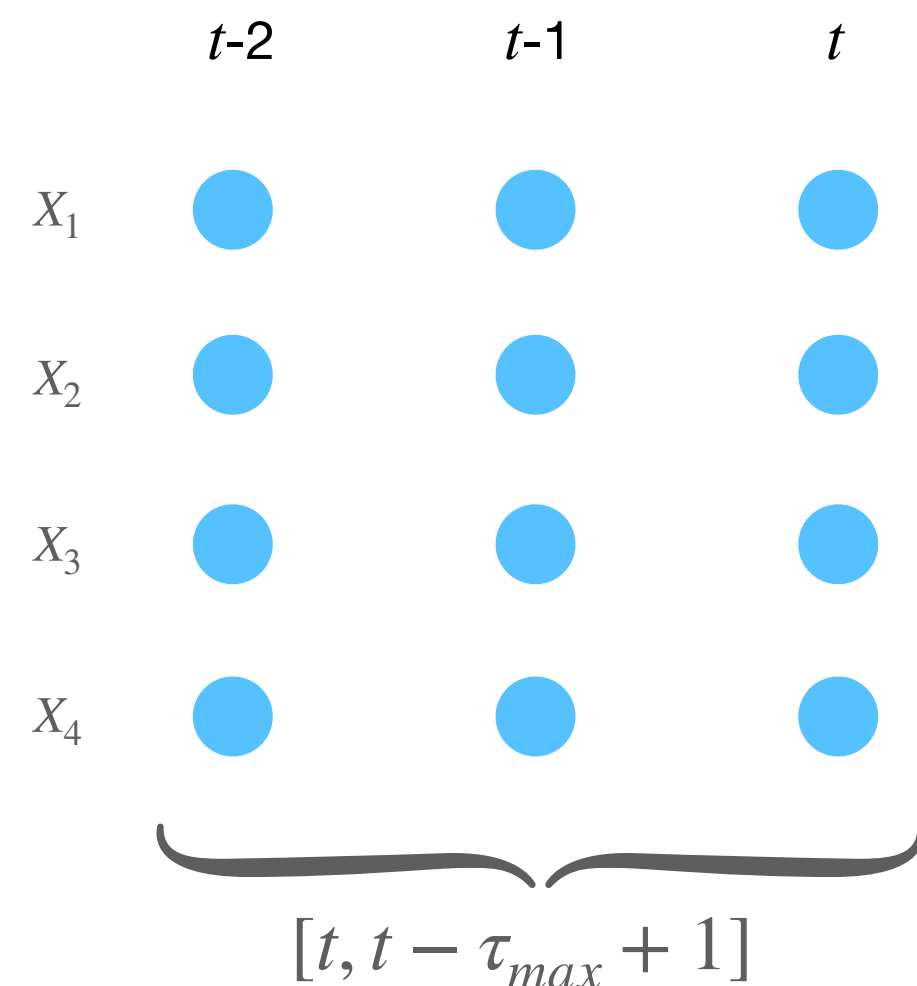
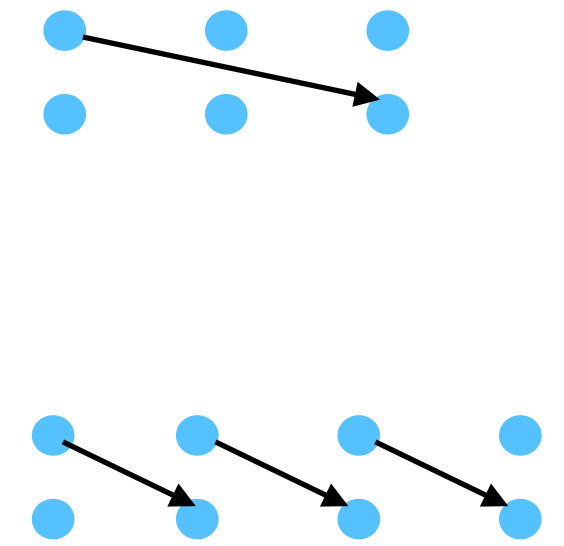


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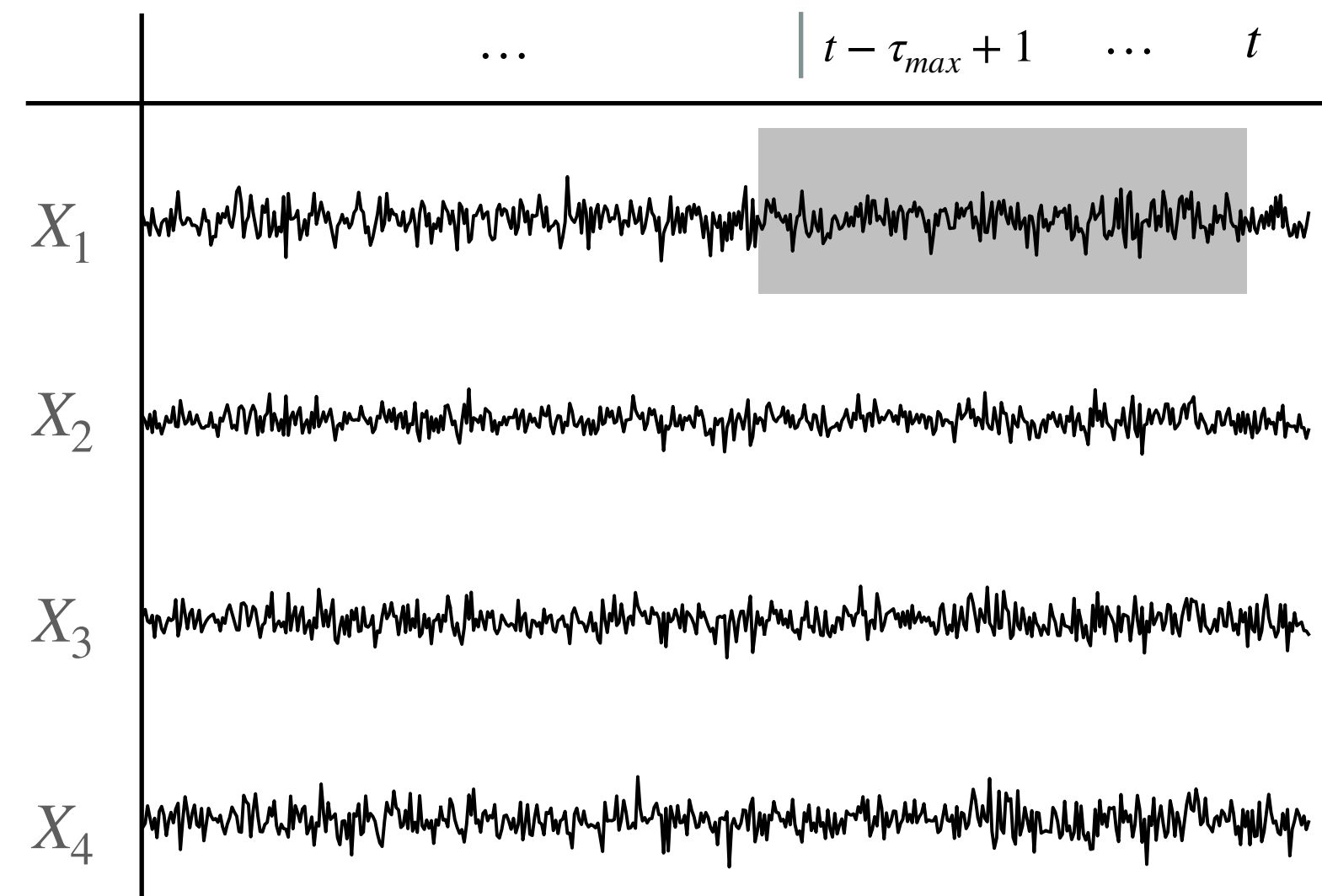
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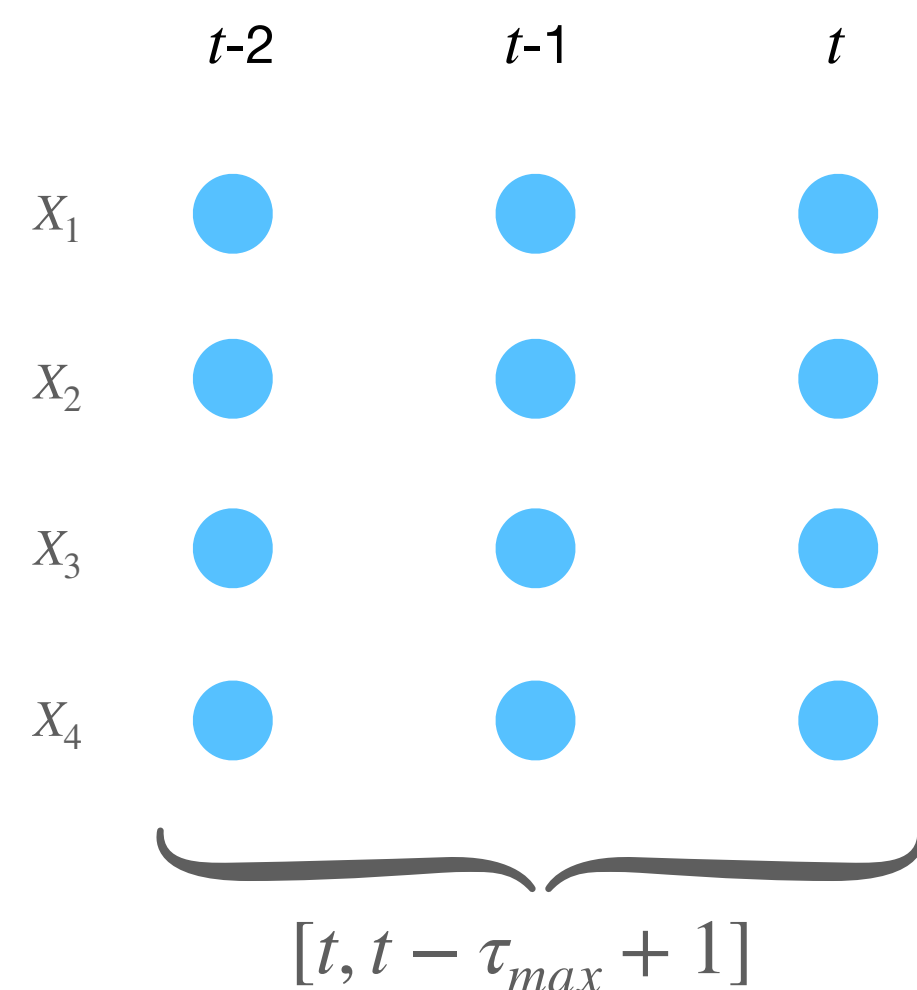
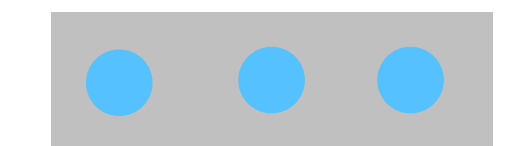
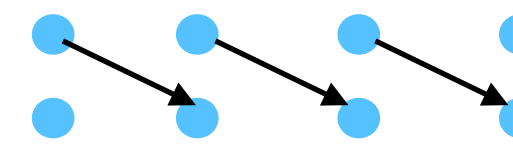
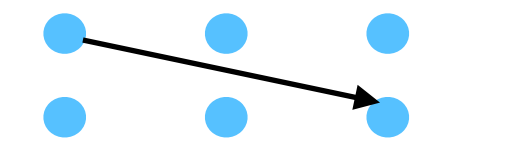


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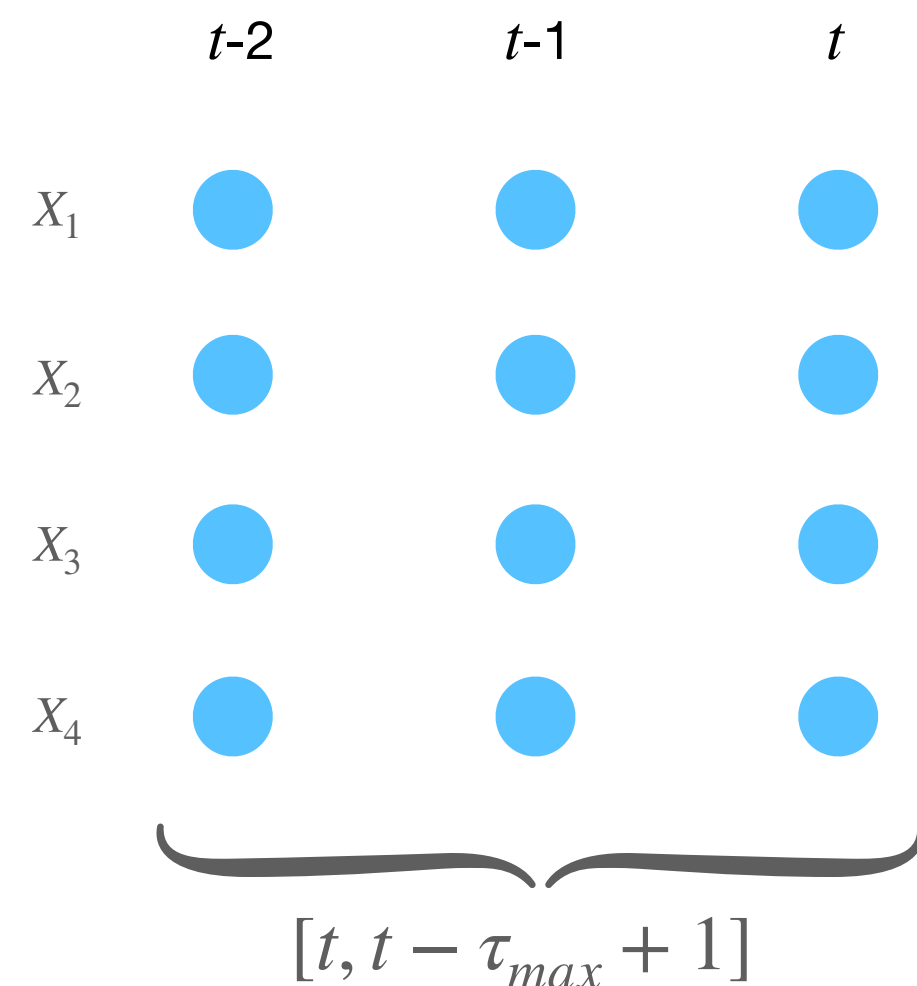
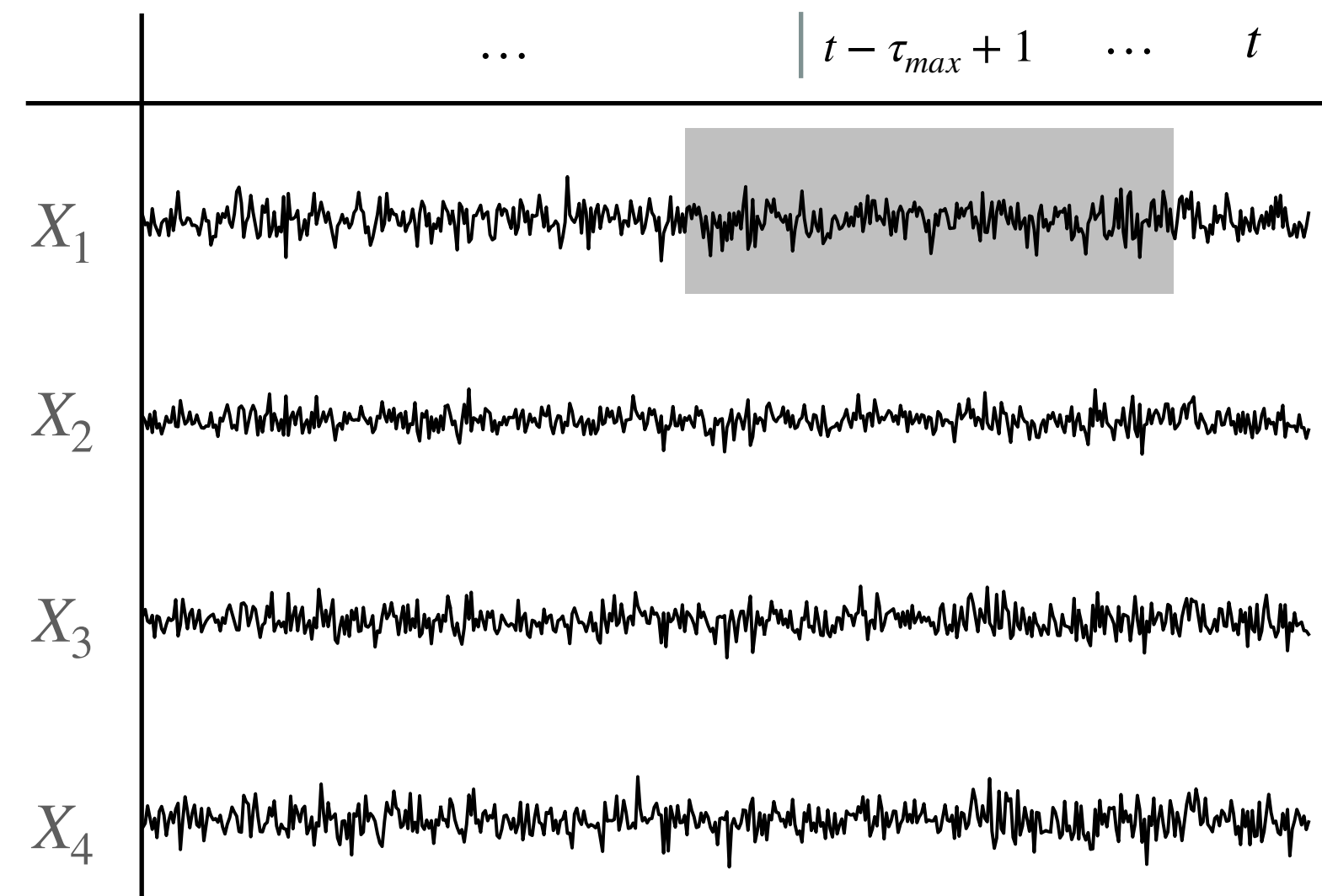


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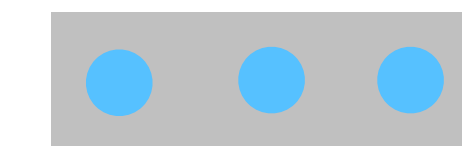
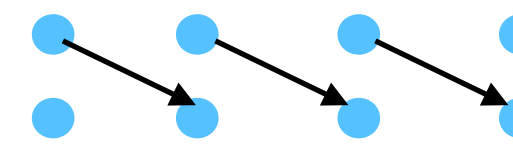
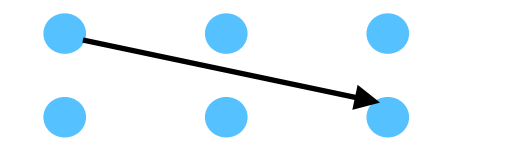


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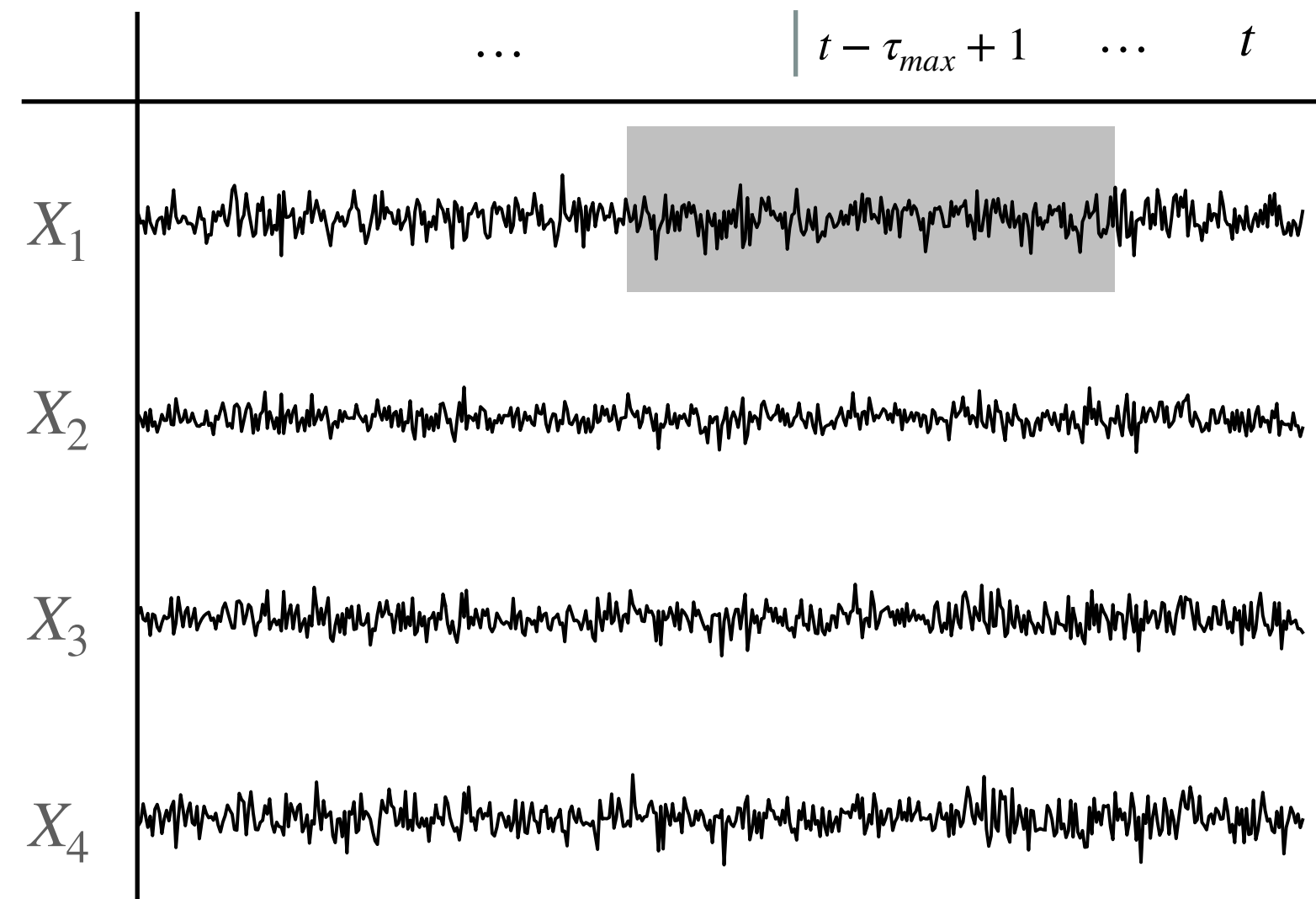
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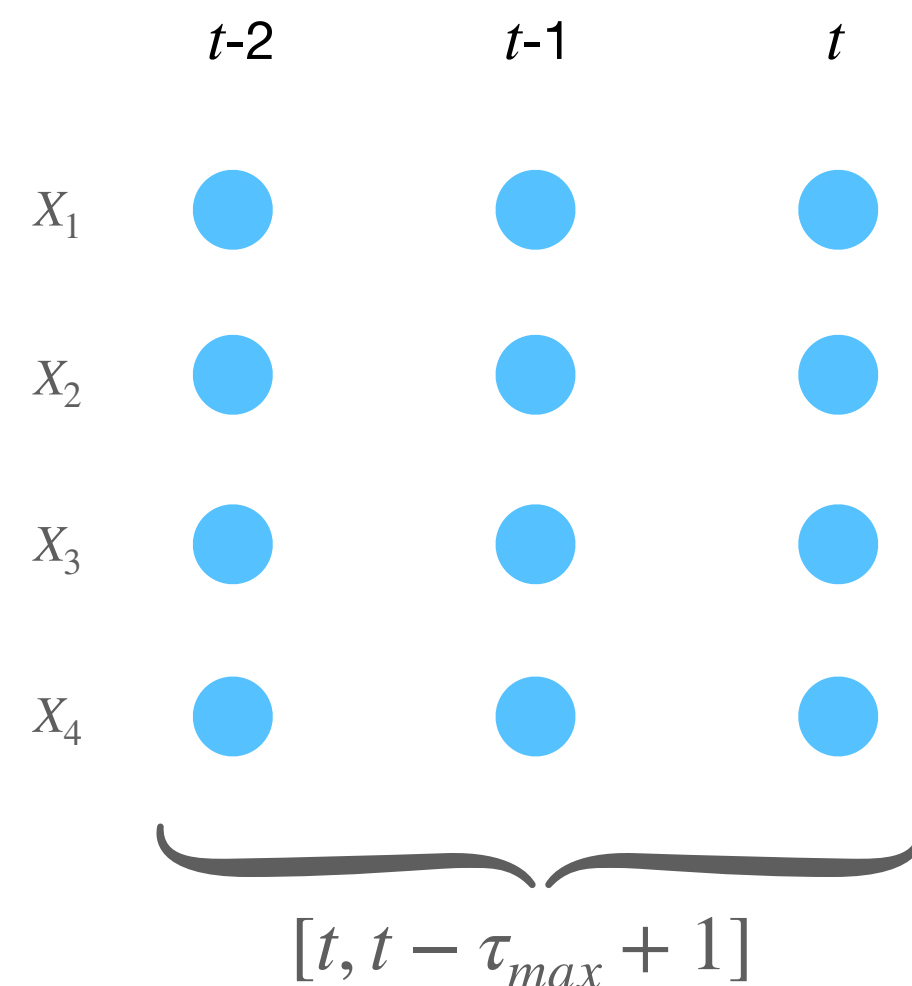
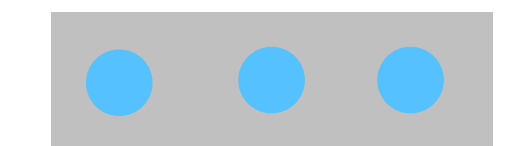
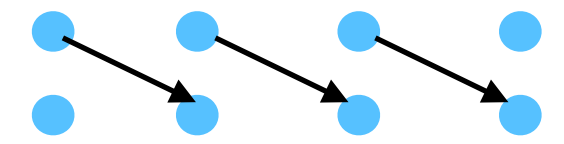
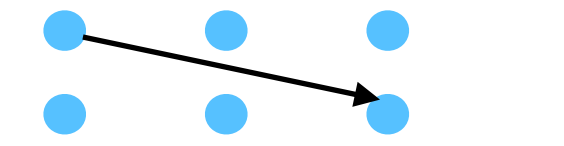


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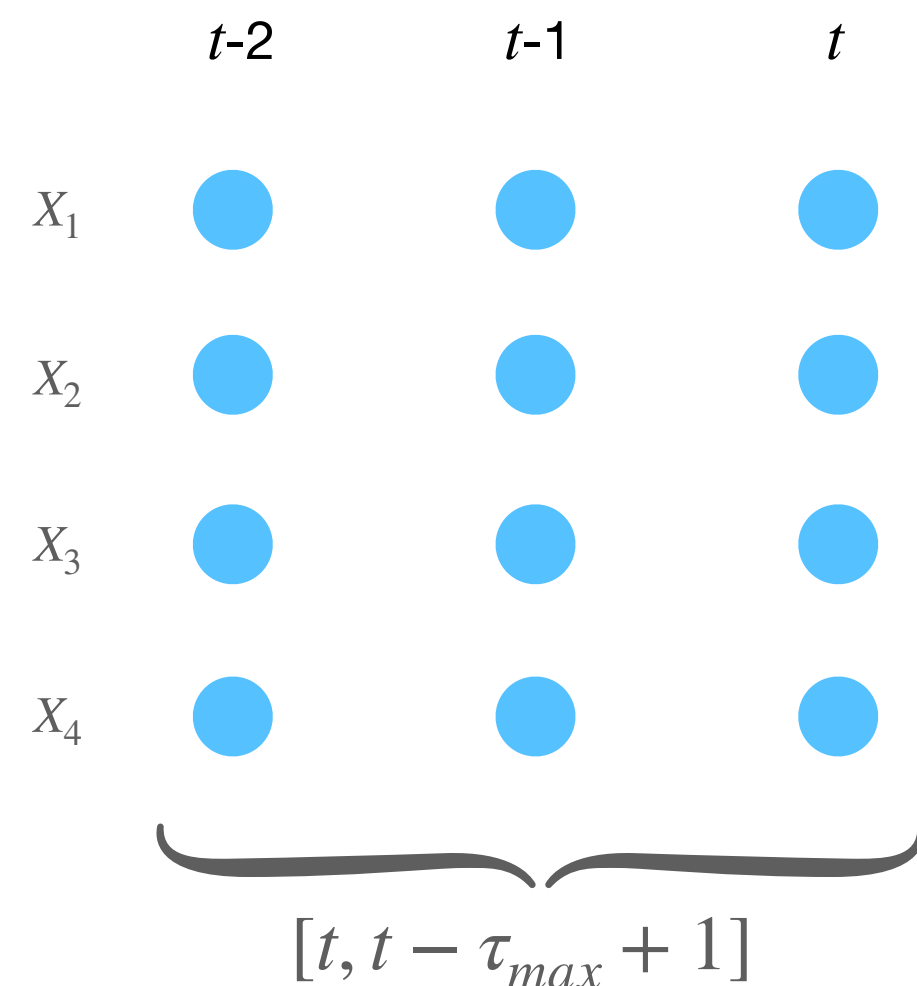
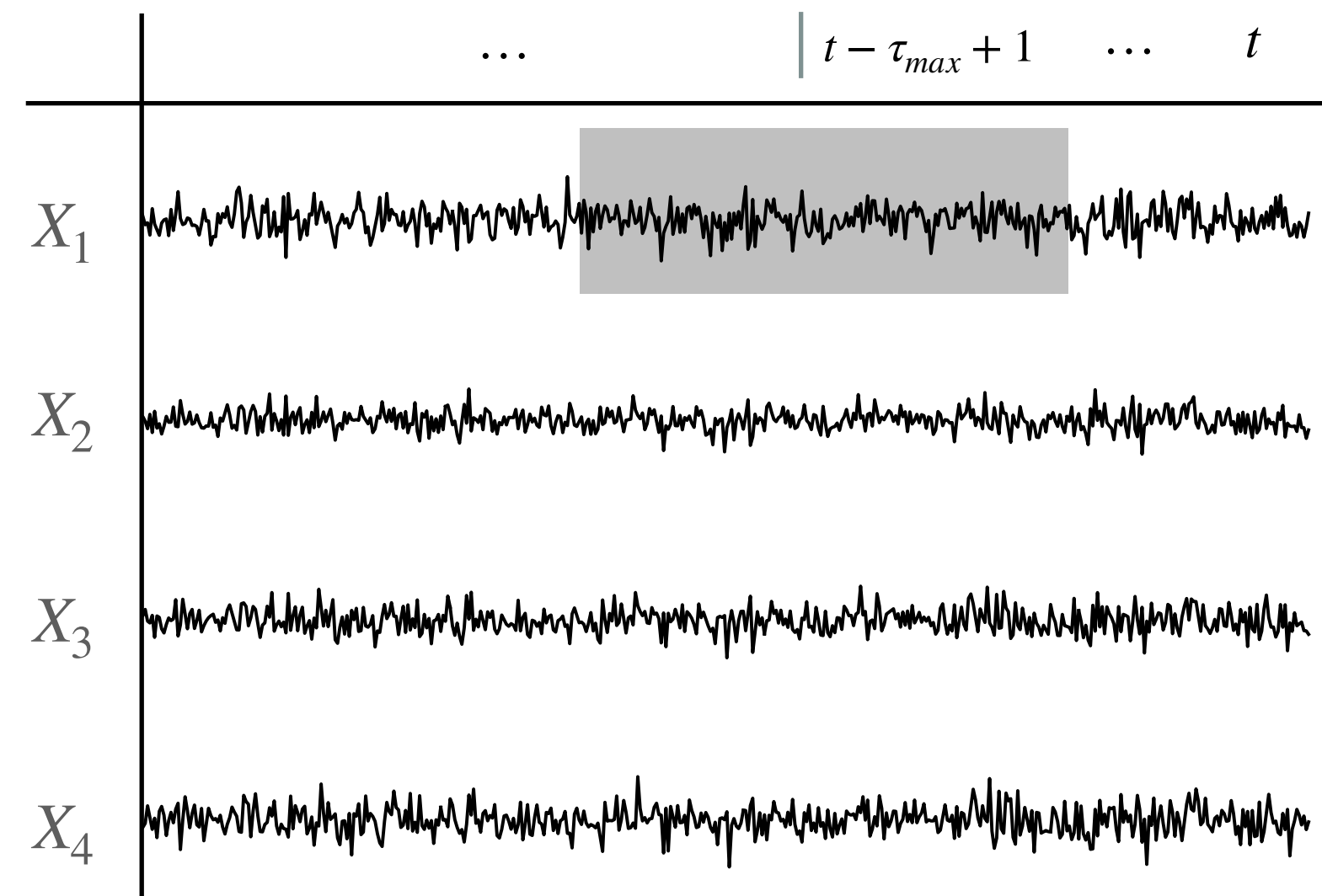


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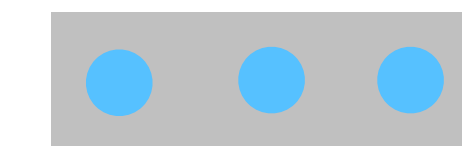
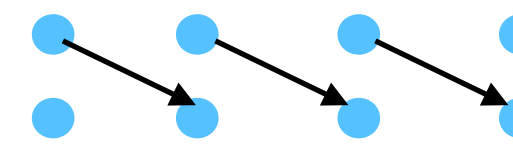
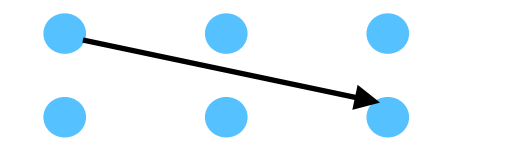


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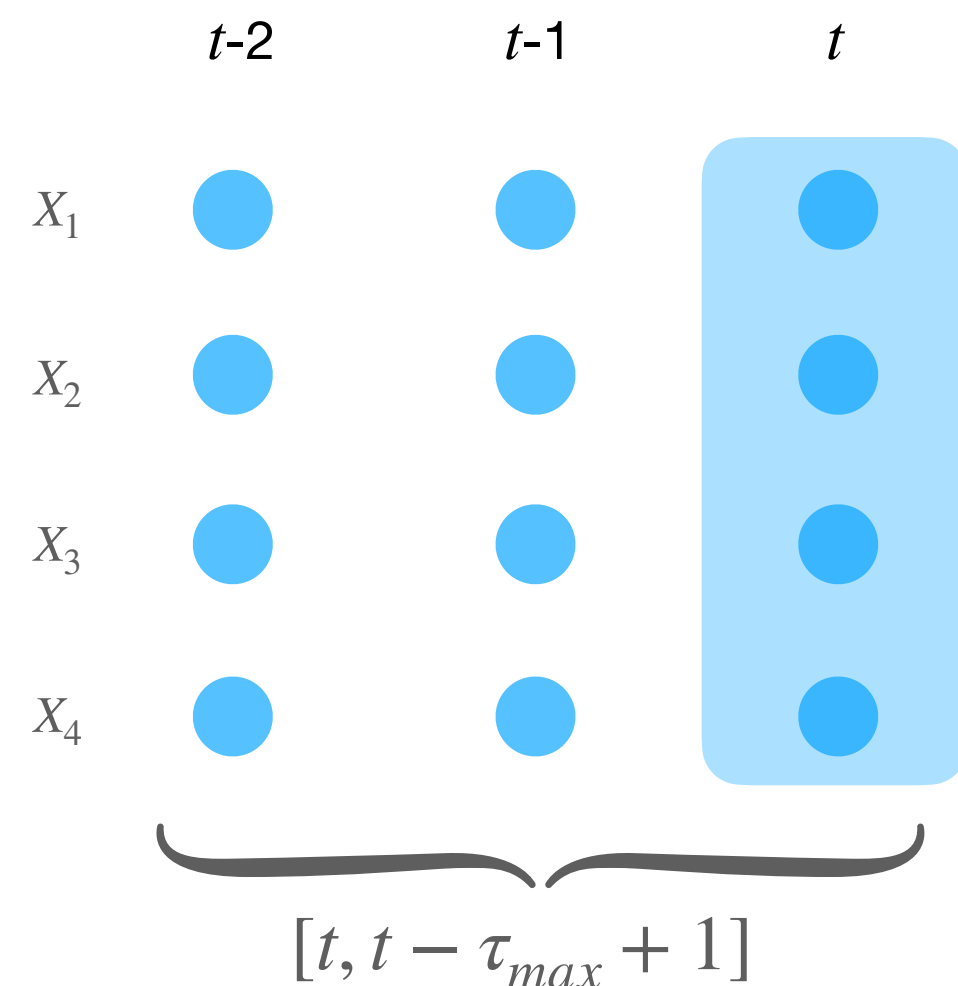
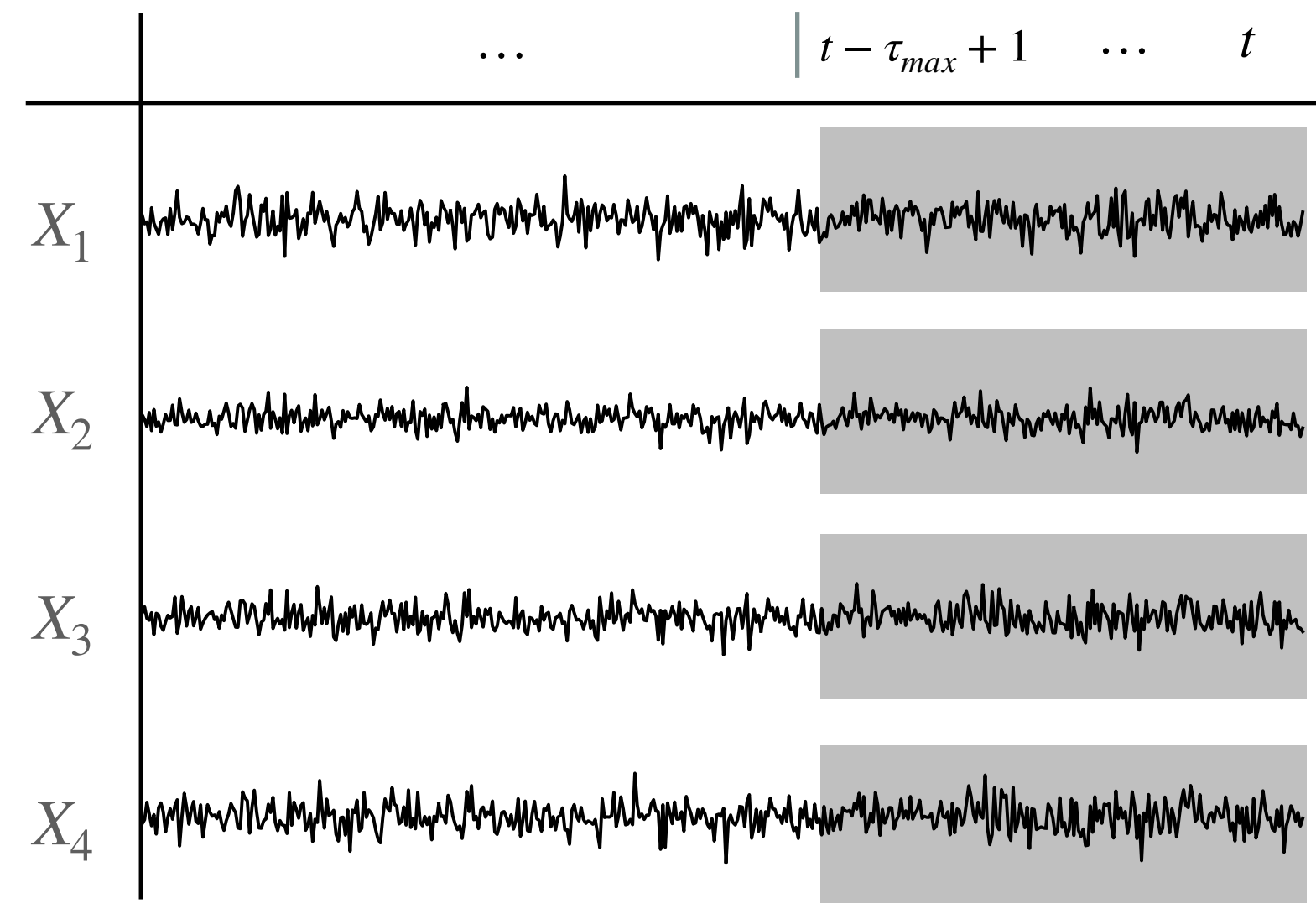


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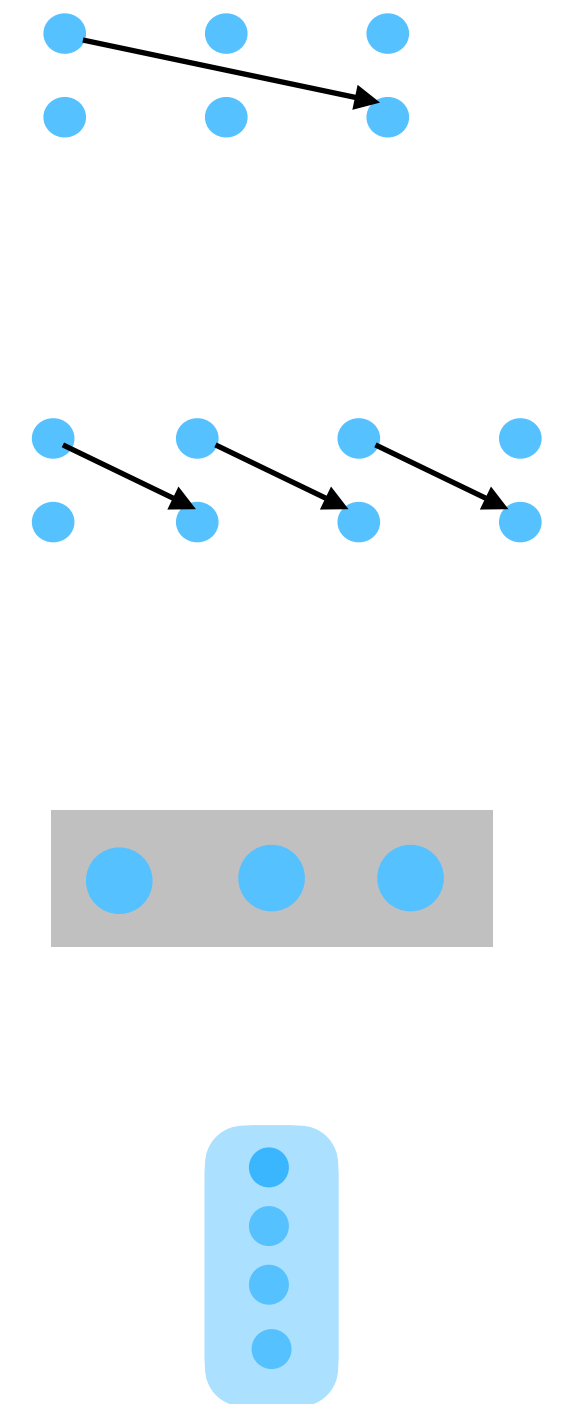


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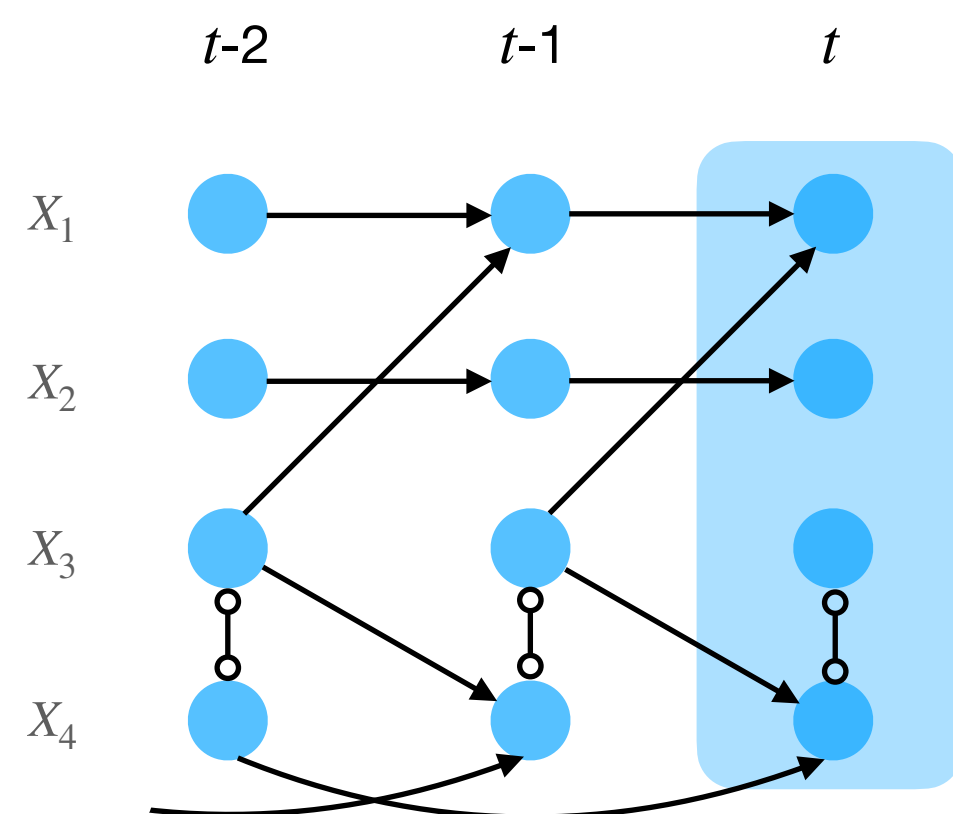
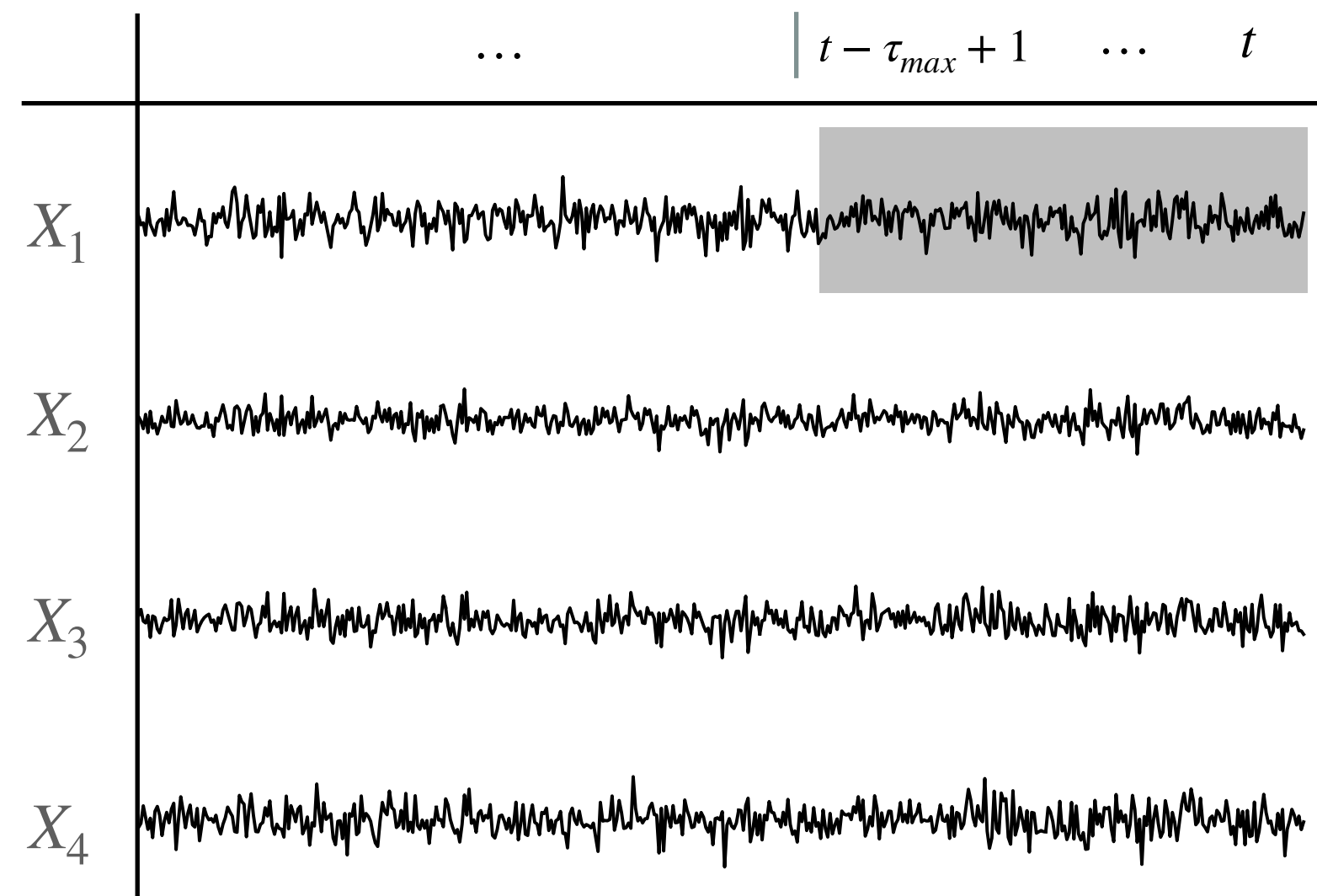
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- Slide the time window  $[t, t - \tau_{max} + 1]$  to generate samples for all  $X_i$ 's
- Devise an algorithm to learn causal parents of the variables at time  $t$ , i.e.  $Pa(X_i^t)$ . (rest of the graph by stationarity)



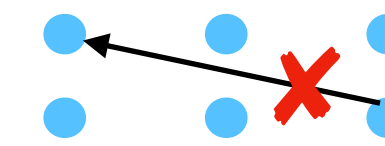
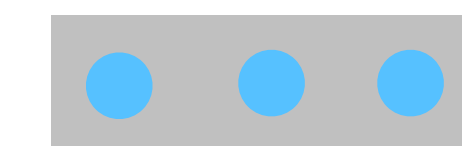
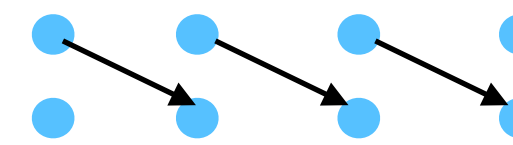
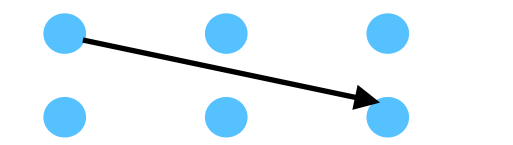


# Causal Inference for Time Series

Basic tenets of time-series causal graph discovery

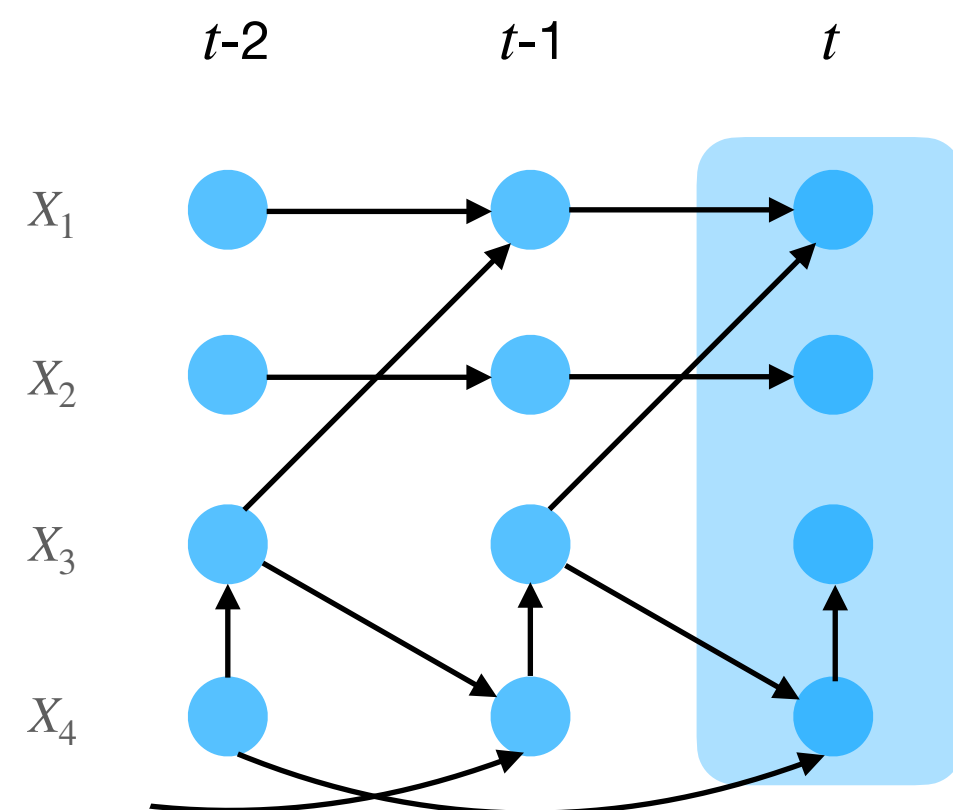
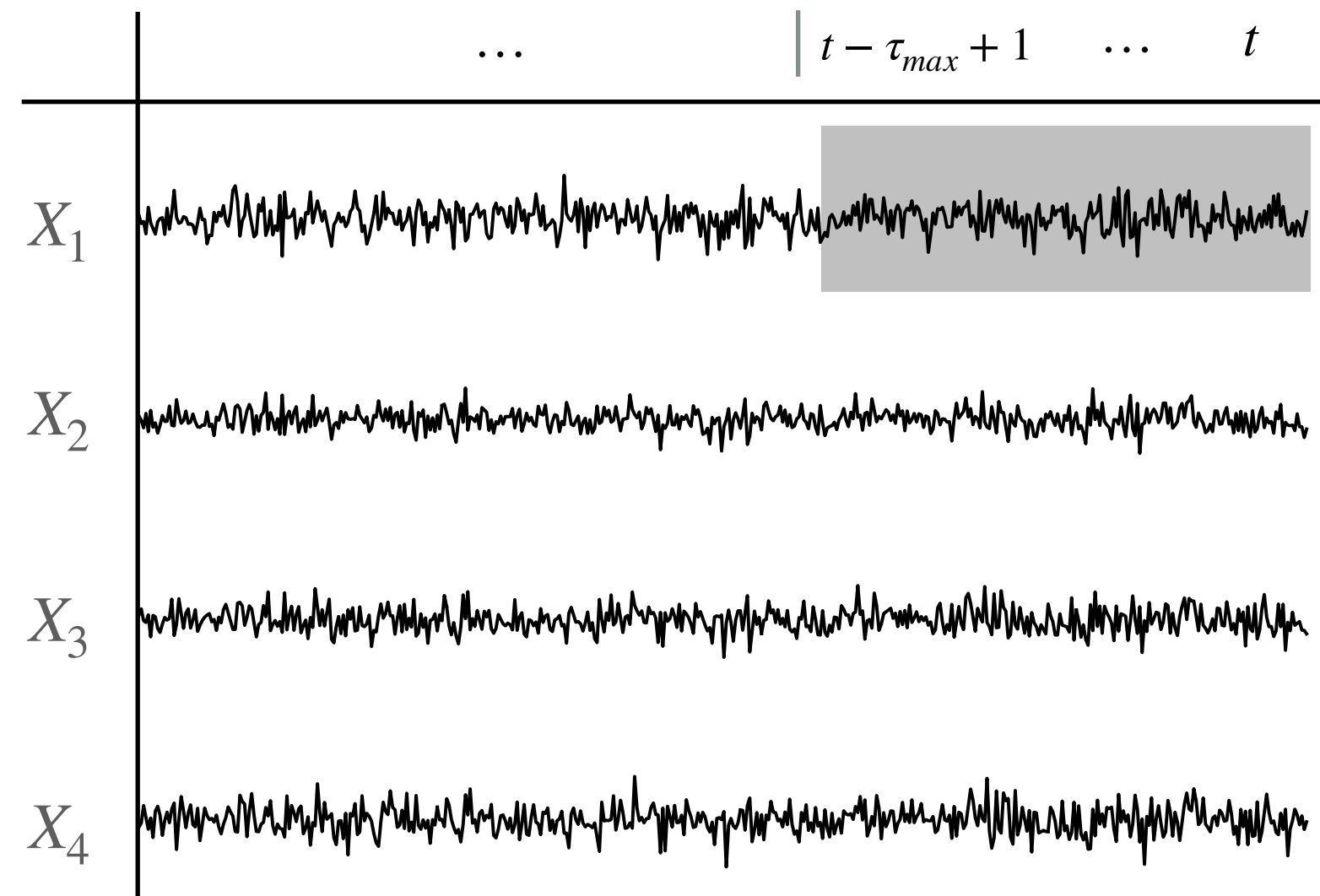


- Start with maximum time lag  $\tau_{max}$ , provided by domain expert or intuition, eg.  $\tau_{max} = 3$ .
- Assuming **causal stationarity**, the graph of interest can be obtained by focusing on the window  $[t, t - \tau_{max} + 1]$
- Slide the time window  $[t, t - \tau_{max} + 1]$  to generate samples for all  $X_i$ 's
- Devise an algorithm to learn causal parents of the variables at time  $t$ , i.e.  $Pa(X_i^t)$ . (rest of the graph by stationarity)
- **Time order** helps orient all but contemporaneous edges

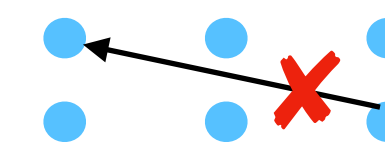
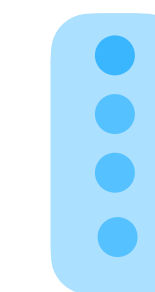
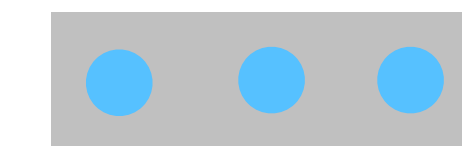
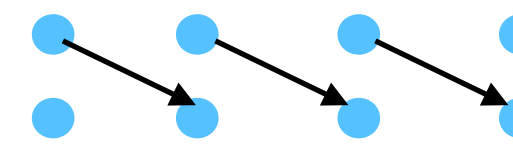
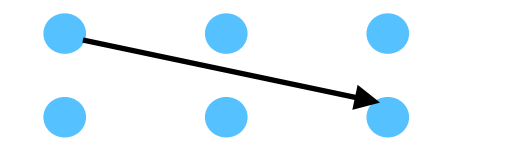


# Causal Inference for Time Series

Basic tenets of time-series causal graph discovery

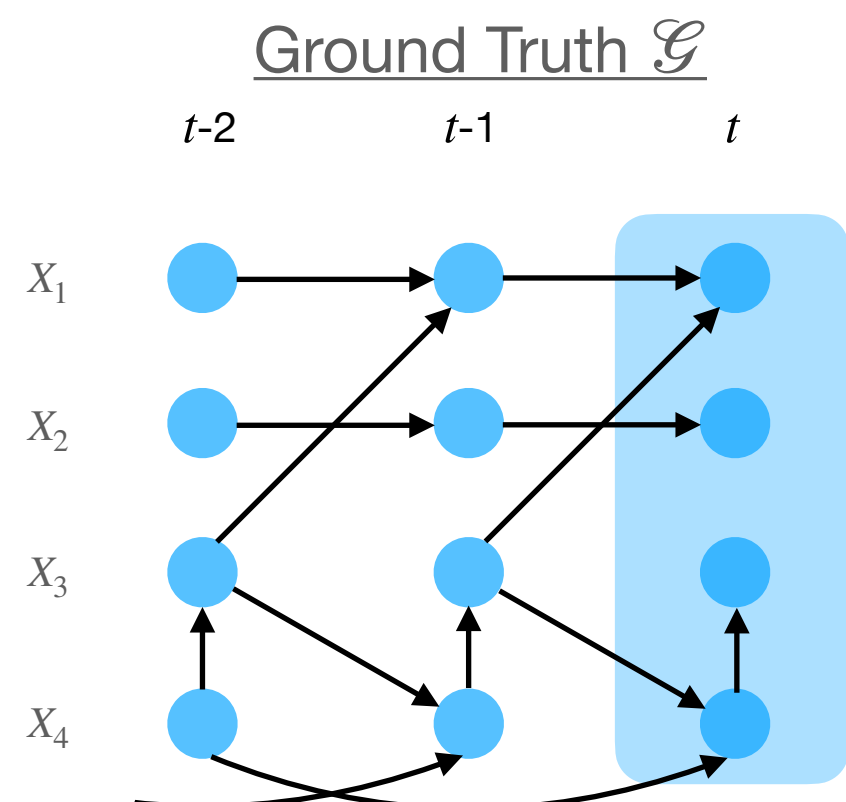
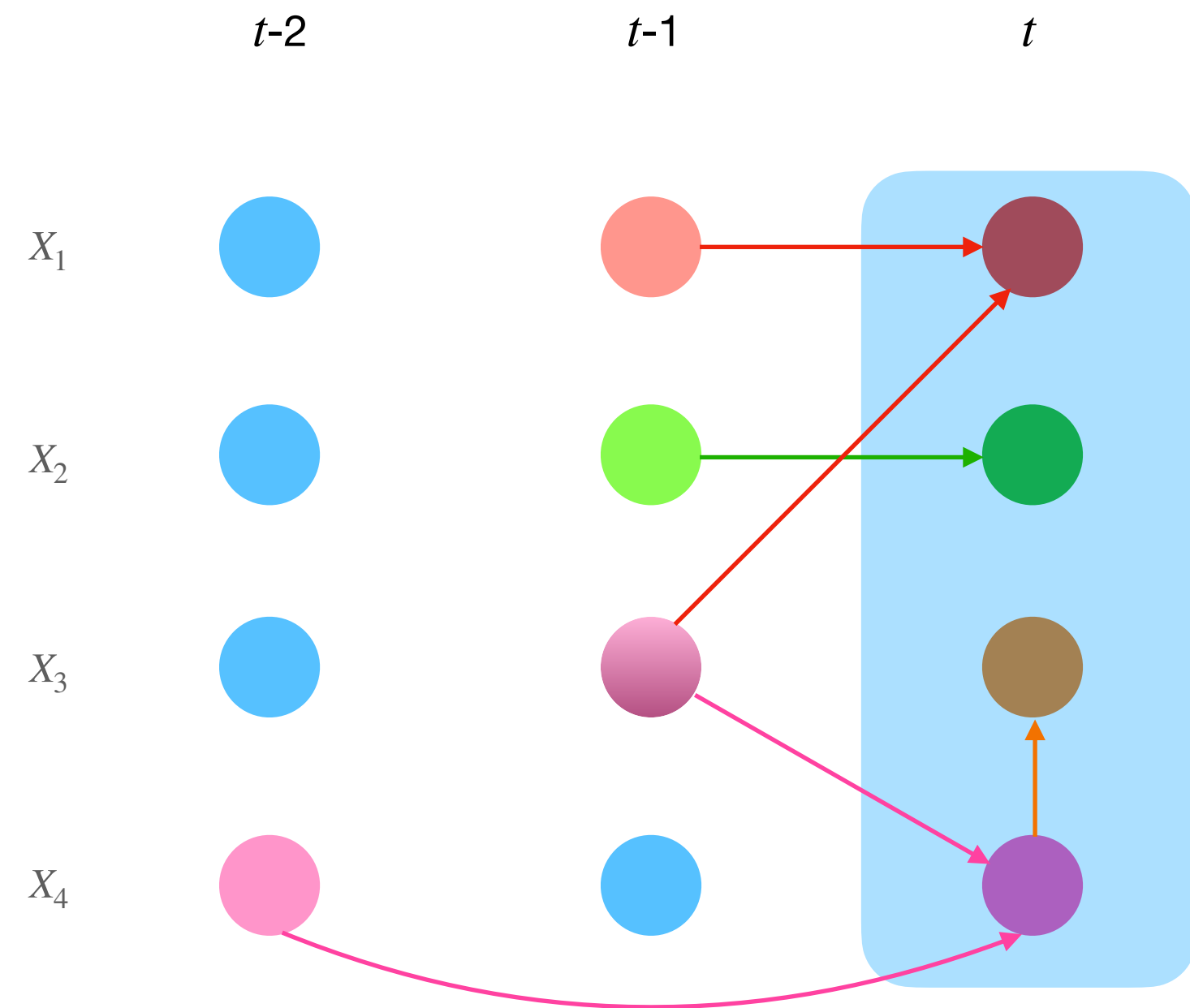


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# Causal Inference for Time Series

## PCMCI Algorithm



- **Problem:** Samples are autocorrelated so detection power of links is low and samples are non-iid so tests not well-calibrated.
  - **Idea:** A momentary conditional independence (MCI) test, instead of a usual conditional independence tests makes samples iid.
- Require:** Parents of all variables, then conduct CI tests.

**Step 1:** Find *superset* of lagged parents of  $X_1, \dots, X_4$  using PC algorithm (and tricks to avoid unnecessary deletion of links)

**Step 2:** Perform MCI test to discover true parents



# Challenges of Time Series Causal Discovery for the Earth System

**Challenges**

**Process:**

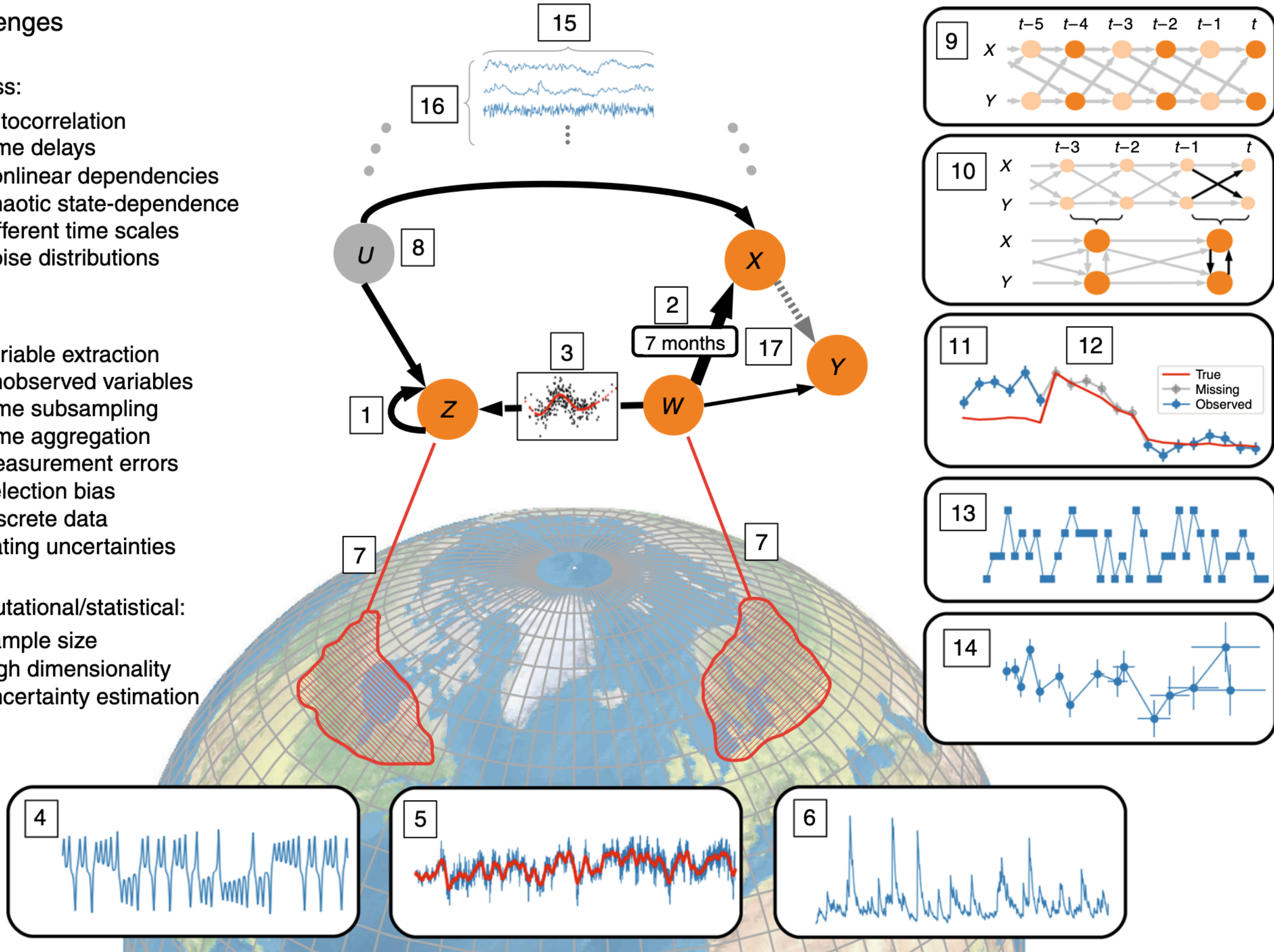
- 1 Autocorrelation
- 2 Time delays
- 3 Nonlinear dependencies
- 4 Chaotic state-dependence
- 5 Different time scales
- 6 Noise distributions

**Data:**

- 7 Variable extraction
- 8 Unobserved variables
- 9 Time subsampling
- 10 Time aggregation
- 11 Measurement errors
- 12 Selection bias
- 13 Discrete data
- 14 Dating uncertainties

**Computational/statistical:**

- 15 Sample size
- 16 High dimensionality
- 17 Uncertainty estimation





# Challenges of Time Series Causal Discovery for the Earth System

## Challenges

### Process:

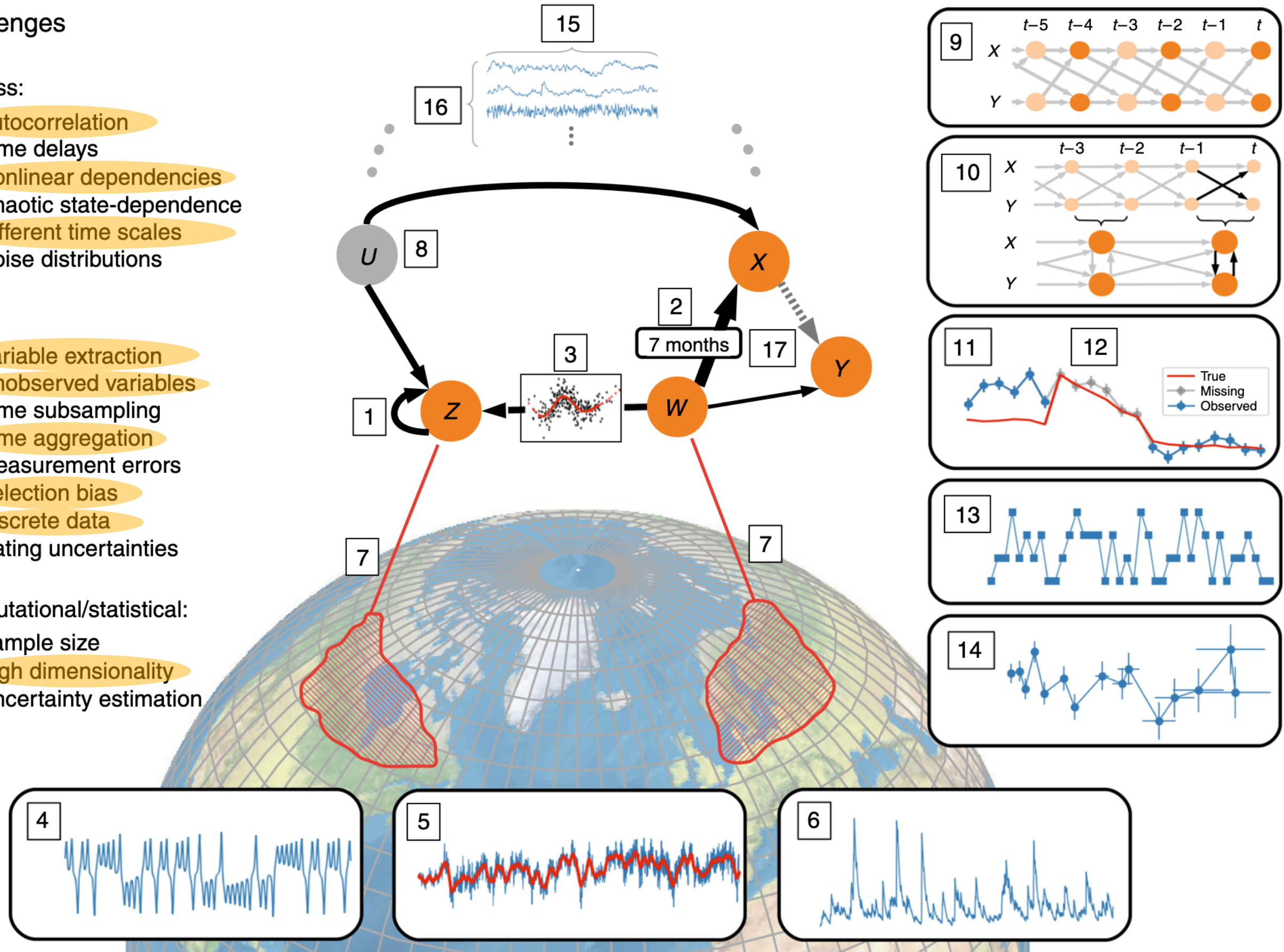
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### Computational/statistical:

- 15 Sample size
- 16 High dimensionality
- 17 Uncertainty estimation



1,3: Detecting and quantifying causal associations in large nonlinear time series datasets, Runge et al, Science, 2019

5: Causal inference for temporal patterns, Domenic-Reiter et al, 2022

5: Causal discovery for time series from multiple datasets with latent contexts, Günther et al, UAI 2023

7: Identifying Linearly-Mixed Causal Representations from Multi-Node Interventions, Bing et al, Clear 2024

8: High-recall causal discovery for autocorrelated time series with latent confounders, Gerhardus et al, Neuritis 2020

10: Discovering contemporaneous and lagged causal relations in autocorrelated nonlinear time series datasets, Runge, UAI 2020

12: Endogenous Regimes and Causal Discovery, Rabel et al, in prep.

13: Non-parametric Conditional Independence Testing for Mixed Continuous-Categorical Variables: A Novel Method and Numerical Evaluation, Popescu et al, 2023

15: Increasing effect sizes of pairwise conditional independence tests between random vectors, Hochsprung et al, UAI 2023

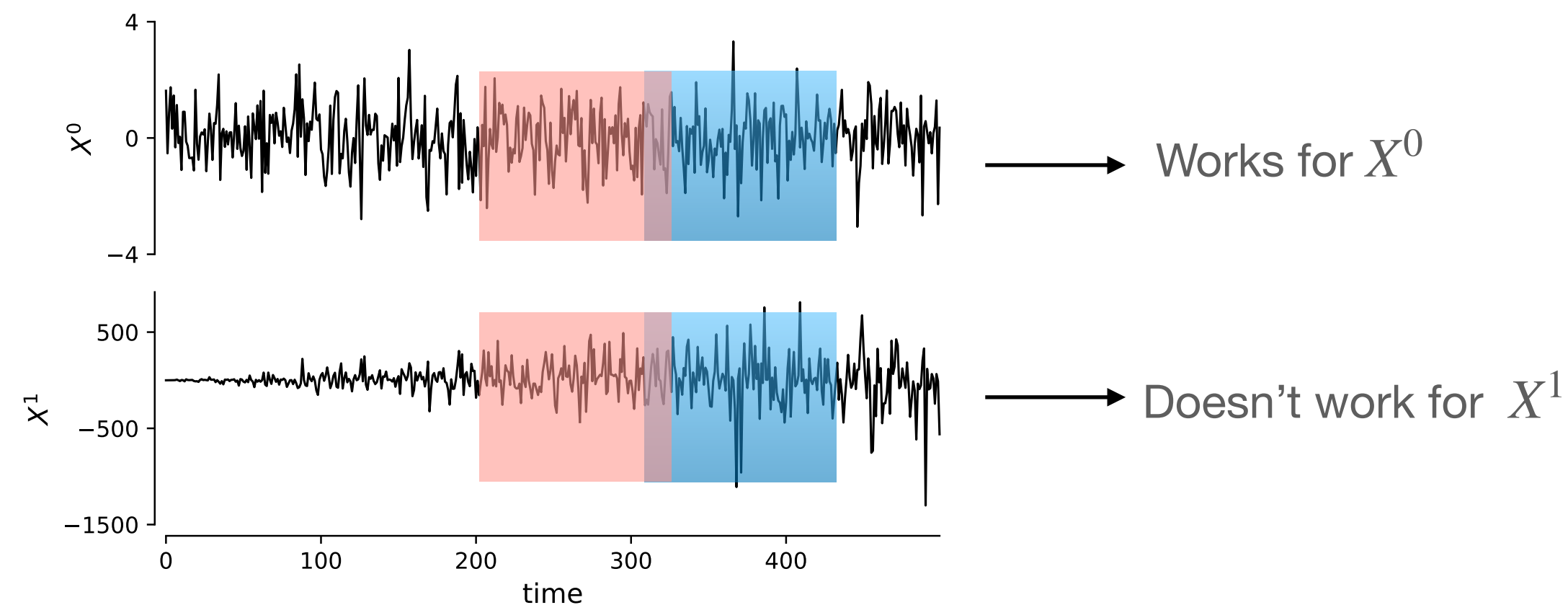
16: Vector causal inference between two groups of variables, Wahl\*, Ninad\* et al, AAI 2023

16: Spatiotemporal Causal Effect Estimation, Herman et al, EGU 2024

# The Non-Stationarity Problem in ts-Causal Discovery

“Causal relationships that change over time”

- Roughly, stationarity implies that causal mechanisms do not change overtime
- Most causal discovery algorithms for time series assume *stationarity*
- Reason for assuming stationarity: In a sliding window approach to generating samples, we need to assume that the samples are identically distributed in order to make statistical inferences



- However, in certain examples, the stationarity assumption becomes unrealistic. Eg. Seasonal variations in climate data.  
Moreover, relaxing this assumption might even aid in orienting links<sup>1</sup>.



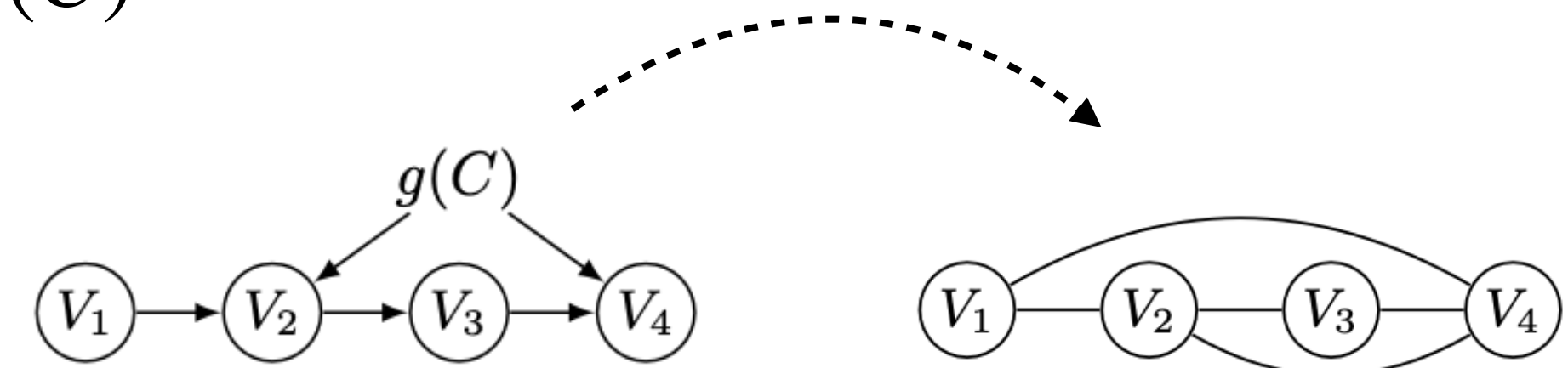


# Dealing with Non-Stationarity: The CD-NOD Idea<sup>1</sup>

Leveraging changing probability distributions

- The time index is interpreted as a special random variable  $C$
- **Pseudo causal sufficiency assumption** : Any latent confounder can be written as a smooth function of time, i.e.,  $g(C)$ .
- Then, the source of non-stationarity is the causal variable  $g(C)$
- **Problem:** Spurious edges:
- **Solution:**
  1. Consider the union of variables  $V_i \cup C$
  2. Test  $V_i \perp C$  to detect non-stationarity
  3. Test  $V_i \perp V_j \mid \mathbf{V}_k \cup C$

⇒ Yields the correct skeleton graph



Example from [1]: When  $g(C)$  is latent, causal discovery may yield spurious edges

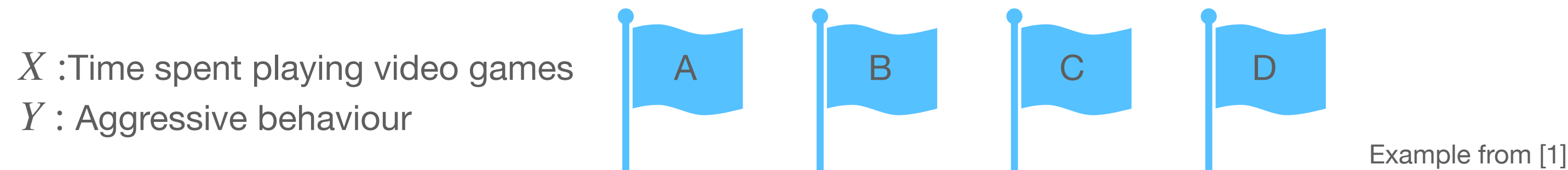


# The Multiple Dataset Problem in Causal Discovery

“Data from multiple environments: boon or bane?”

- Data sets of the same variables can come from different *environments/domains/contexts*<sup>1,2,3,4</sup>.

Eg. Data for different individuals (in health, econometrics), data from different countries (in sociology, macroeconomics). . .



- Given such ‘heterogenous’ data, we can make different kinds of causal queries:
  1. What is the causal structure *within* each data set?
  2. What is the causal structure *across* data sets?<sup>1,3</sup>
  3. Given the causal structure of one data set, what (if anything) can we say about the causal structure of another data set?<sup>2</sup>
  4. How can we leverage the *invariance* of certain causal relationships across data sets?<sup>4</sup>

1: Mooij et al’20, JMLR  
 2: Bareinboim’16, PNAS  
 3: Huang\*,Zhang\* et al’20, JMLR  
 4. Peters et al’16, JRSS. . .



# Application of the Multiple Dataset Problem

## A River Catchment Example

- A *catchment* is an area of land where water collects when it rains, often bounded by hills.
- The characteristics of catchments are highly heterogeneous (area, slope, etc.).  
Catchment behaviour also depends on regional climate and other meteorological variables.
- Can we make causal inferences about the causal drivers of catchment behaviour?

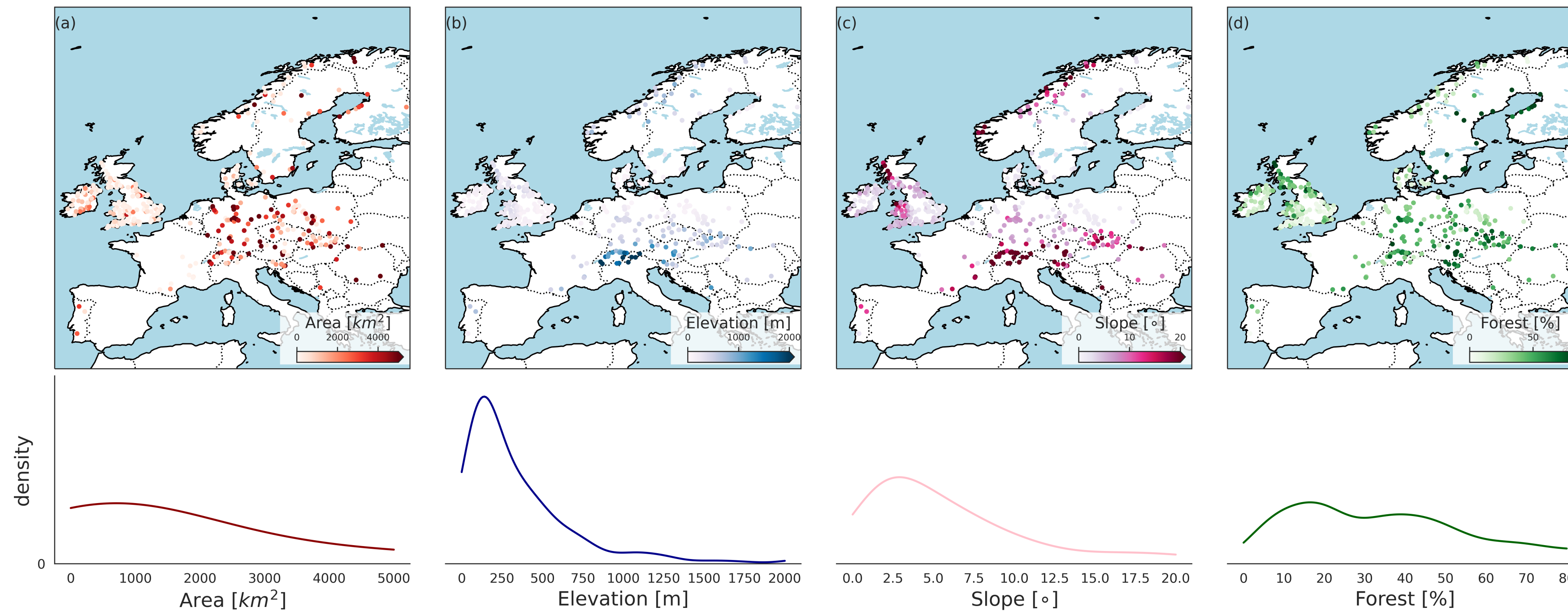


Figure from [1]: An overview of the European catchment characteristics (eg. Area, elevation, etc.)

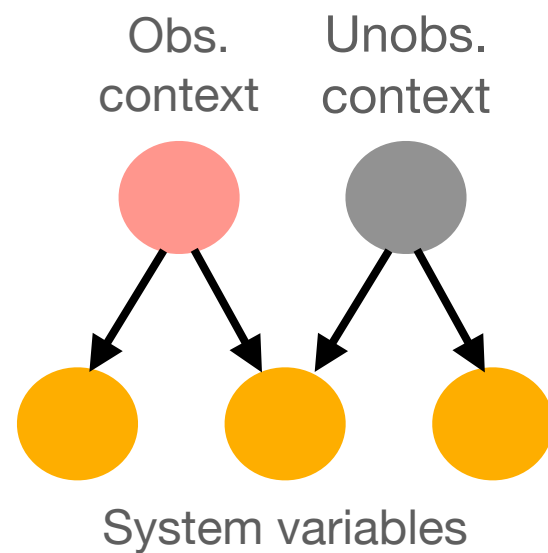




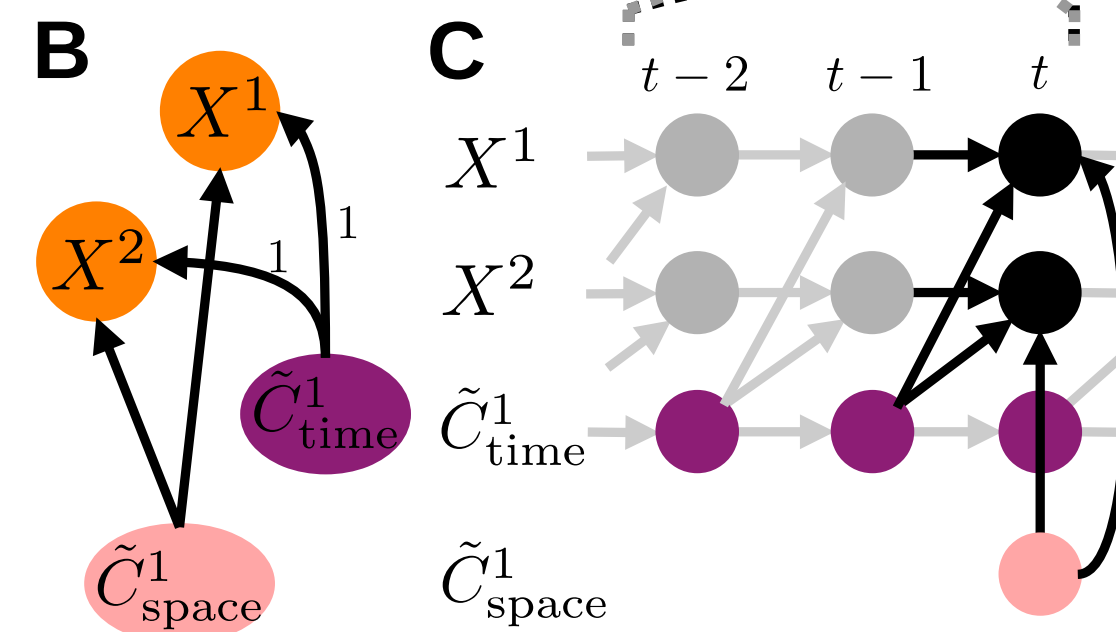
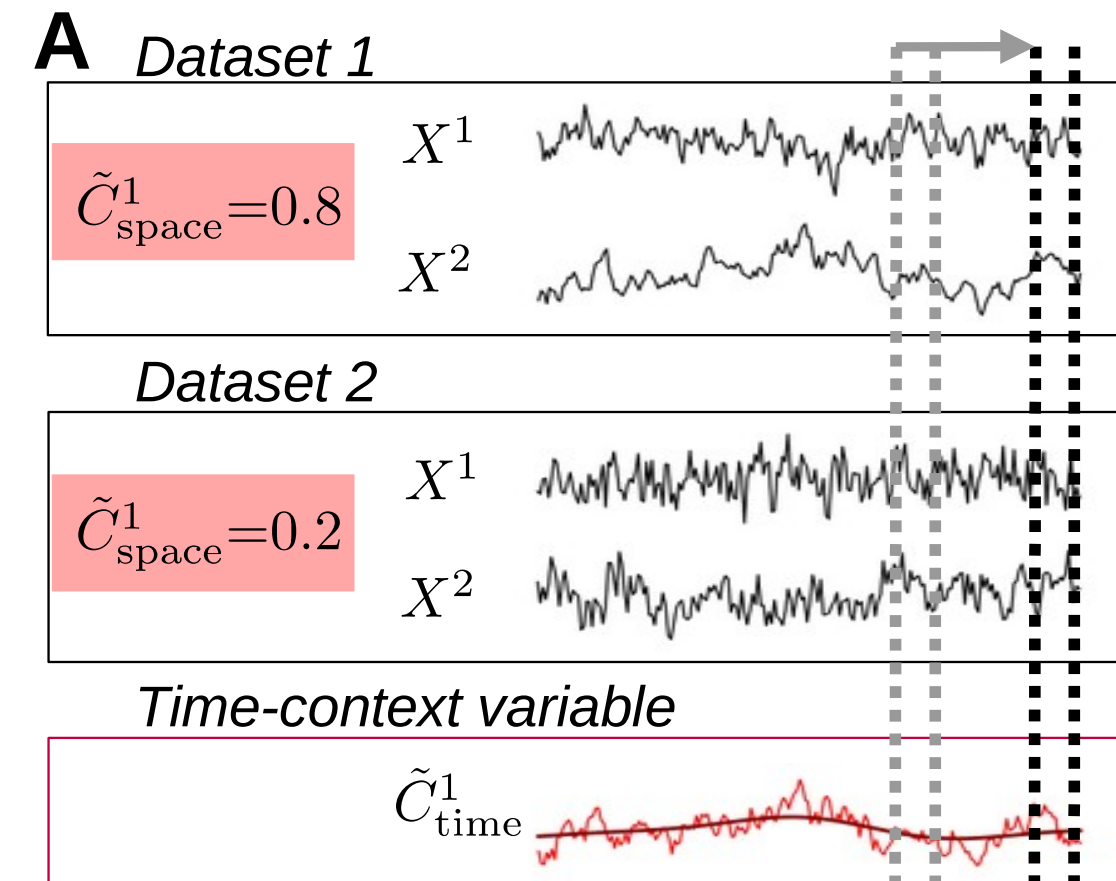
# J(oint)-PCMCI+<sup>1</sup>

## Schematic Idea:

- Introduce ‘spatial’ and ‘temporal’ context variables (Space indicates the data set label dimension, not necessarily physical space)
- Generalise DAGs on system variables to the case with observed as well as unobserved context variables



- For the unobserved contexts introduce a ‘dummy’ variable to keep track of the time index or the data set label.  
 Spatial contexts  $\Rightarrow$  Space dummy  
 Temporal contexts  $\Rightarrow$  Time dummy
- Apply the fixed effect regression idea (from econometrics) to de-confound system variables (while taking care of faithfulness violations due to determinism)



$$\mathbf{X}_t^d := \mathbf{f}(Pa_{\mathbf{X}}(\mathbf{X}_t^d), Pa_{\tilde{C}_{\text{time}}}(\mathbf{X}_t^d), Pa_{\tilde{C}_{\text{space}}}(\mathbf{X}_t^d), \eta_t^d)$$

$$\tilde{C}_{\text{time},t} := \mathbf{g}(Pa_{\tilde{C}_{\text{time}}}(\tilde{C}_{\text{time},t}), \eta_{\text{time},t})$$

$$\tilde{C}_{\text{space}}^d := \mathbf{h}(Pa_{\tilde{C}_{\text{space}}}(\tilde{C}_{\text{space}}), \eta_{\text{space}}^d)$$



# Causal Effect Estimation

“How *much* does  $X$  cause  $Y$ ?”

- **Causal effect** of  $X$  on  $Y$  is defined as  $CE(X \rightarrow Y) = \frac{\partial}{\partial x} E(Y | do(X = x))$ , where  $E(X) := \int x \cdot p(x) dx$ .

Example:

$$X := \eta_X$$

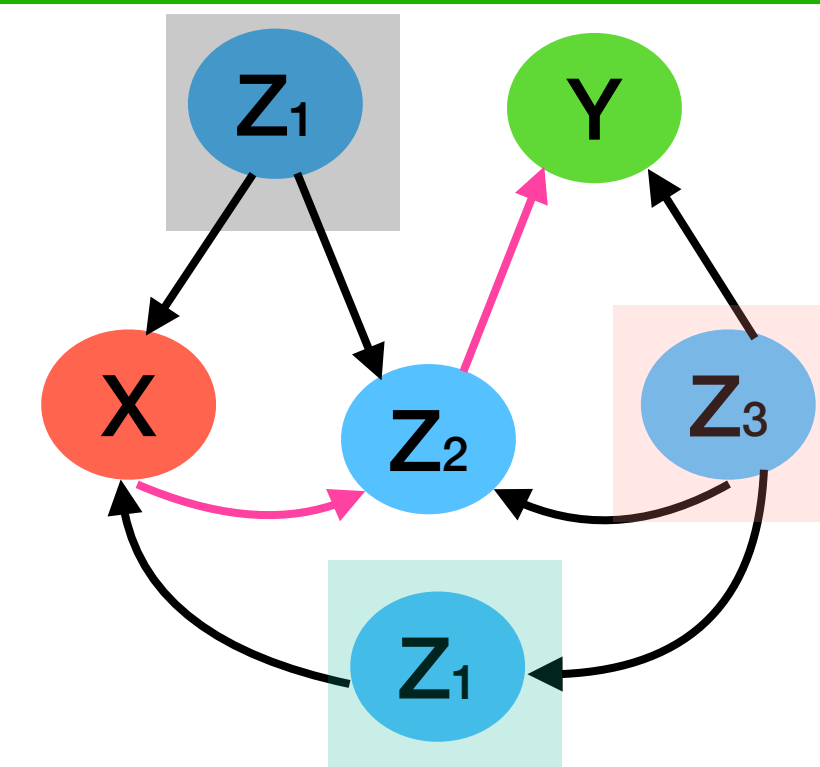
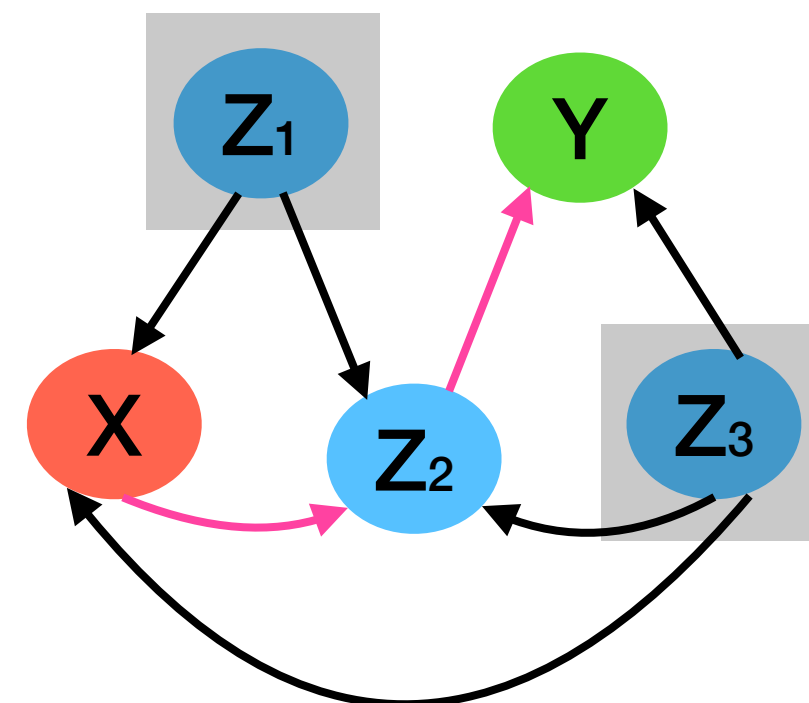
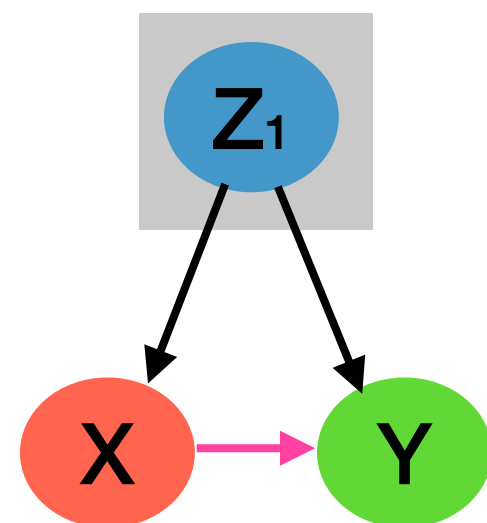
$$Y := b \cdot X + \eta_Y \implies CE(X \rightarrow Y) = b$$

(Linear causal effects can be read off from structural causal model)

- Given the causal graph, how to determine the causal effect by statistical methods (i.e. without interventions)?

$$\implies \text{Adjustment Set}^1 \mathbf{Z} \text{ for } CE(X \rightarrow Y) \text{ is defined by } P(Y | do(X)) = \int P(Y | X, \mathbf{Z}) P(\mathbf{Z}) d\mathbf{Z}$$

- Many adjustment sets satisfy the defining property (i.e. are unbiased), but which is the optimal set (i.e. has least variance)?  $\implies$  **Optimal adjustment set theory**<sup>2</sup>

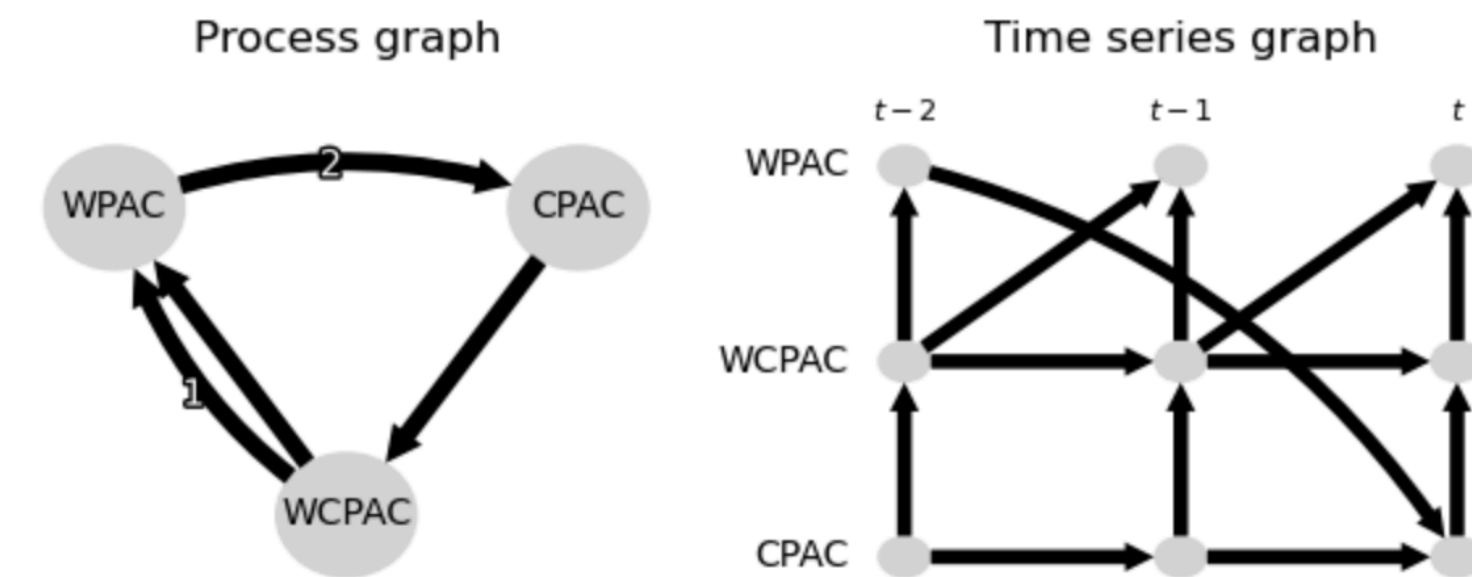
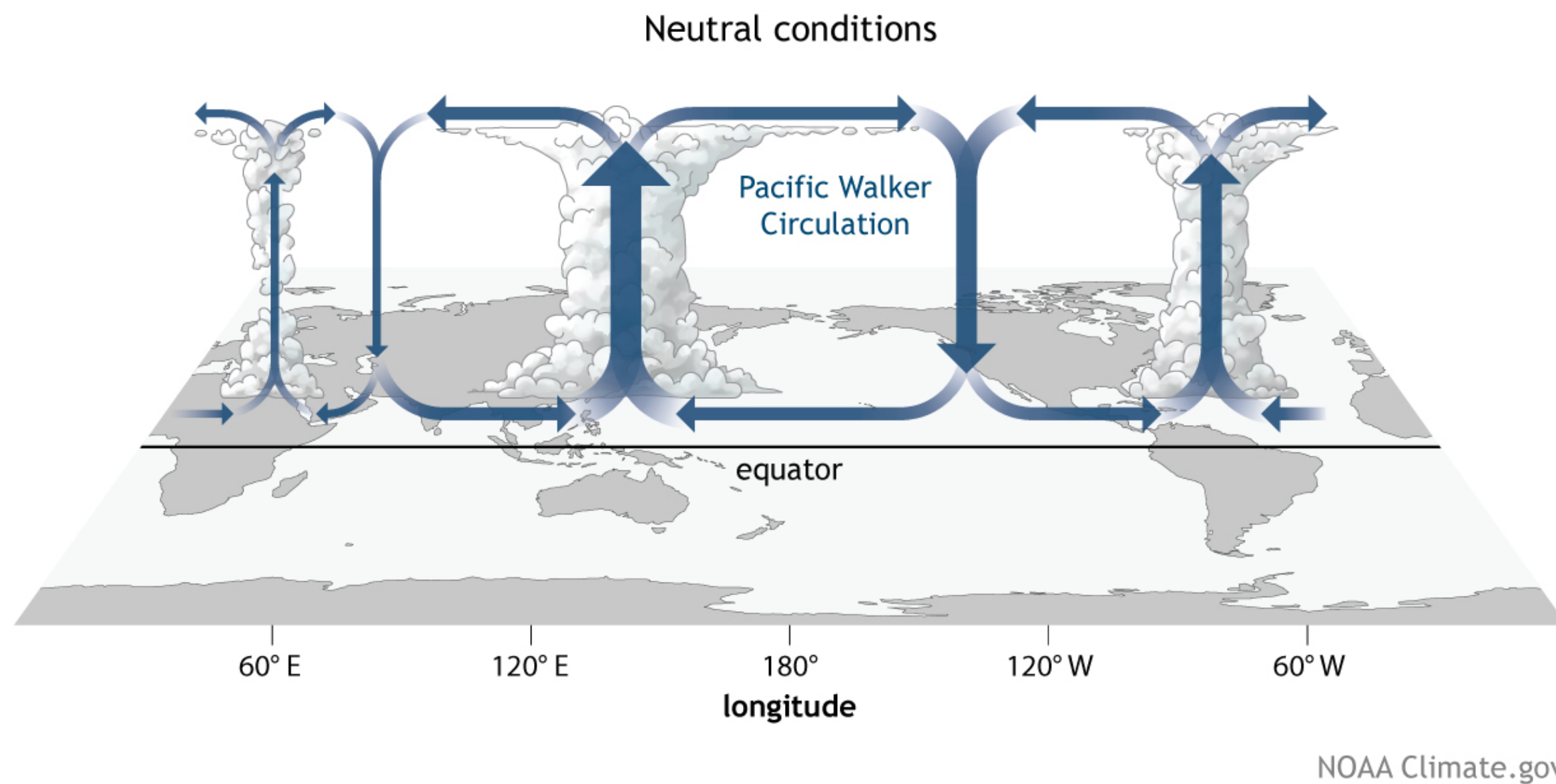


1: Works of Pearl, Shpitser etc...

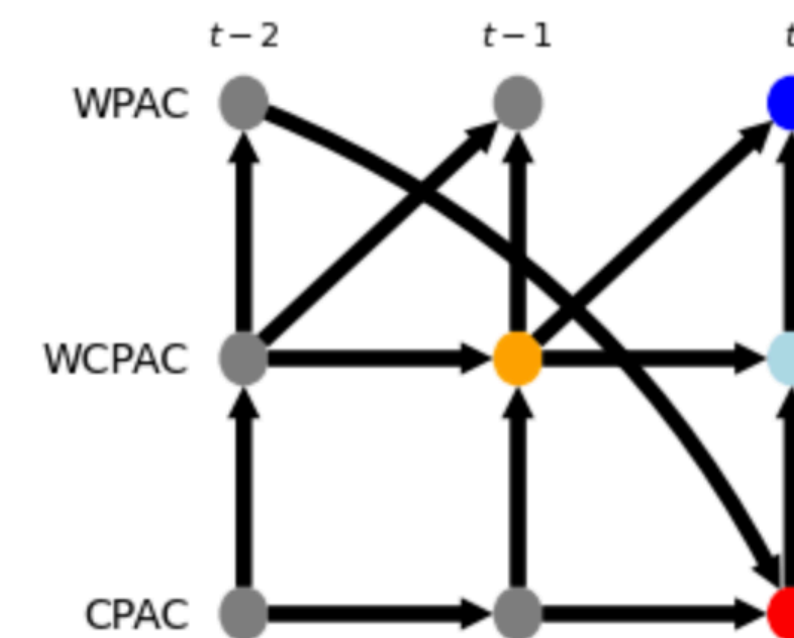
2: Works of Maathuis, Colombo, Perkovic, Henckel, Runge etc...

# Causal Effect Estimation in the Climate: Walker Circulation

- Walker circulation is a model of air flow in the lower atmosphere in the tropics
- We focus on clock-wise circulation of falling air masses in the Central Pacific (CPAC), westward surface tradewinds in the Western-central pacific (WCPAC), and rising air masses in the western Pacific (WPAC).



$X = [(['CPAC', 0])] \text{ -----> } Y = [(['WPAC', 0])]$   
 $Oset = [(['WCPAC', -1])]$



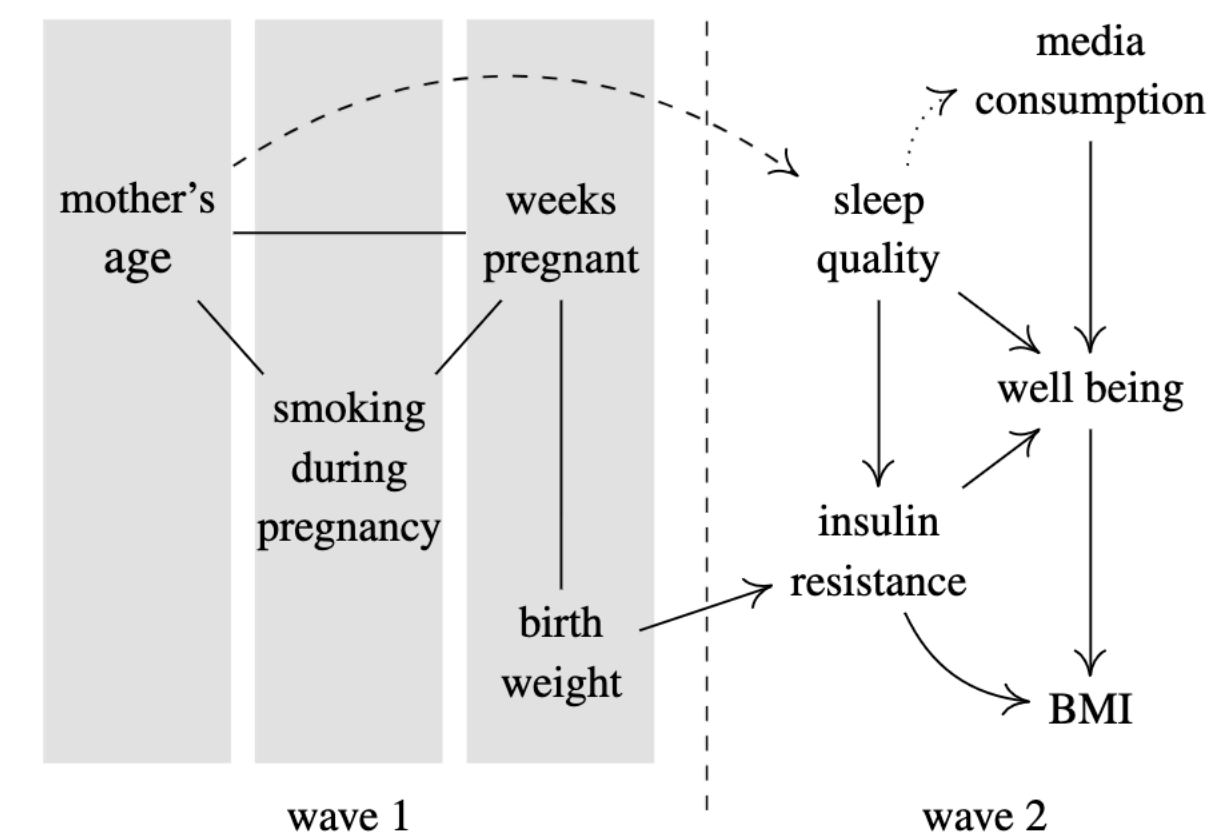
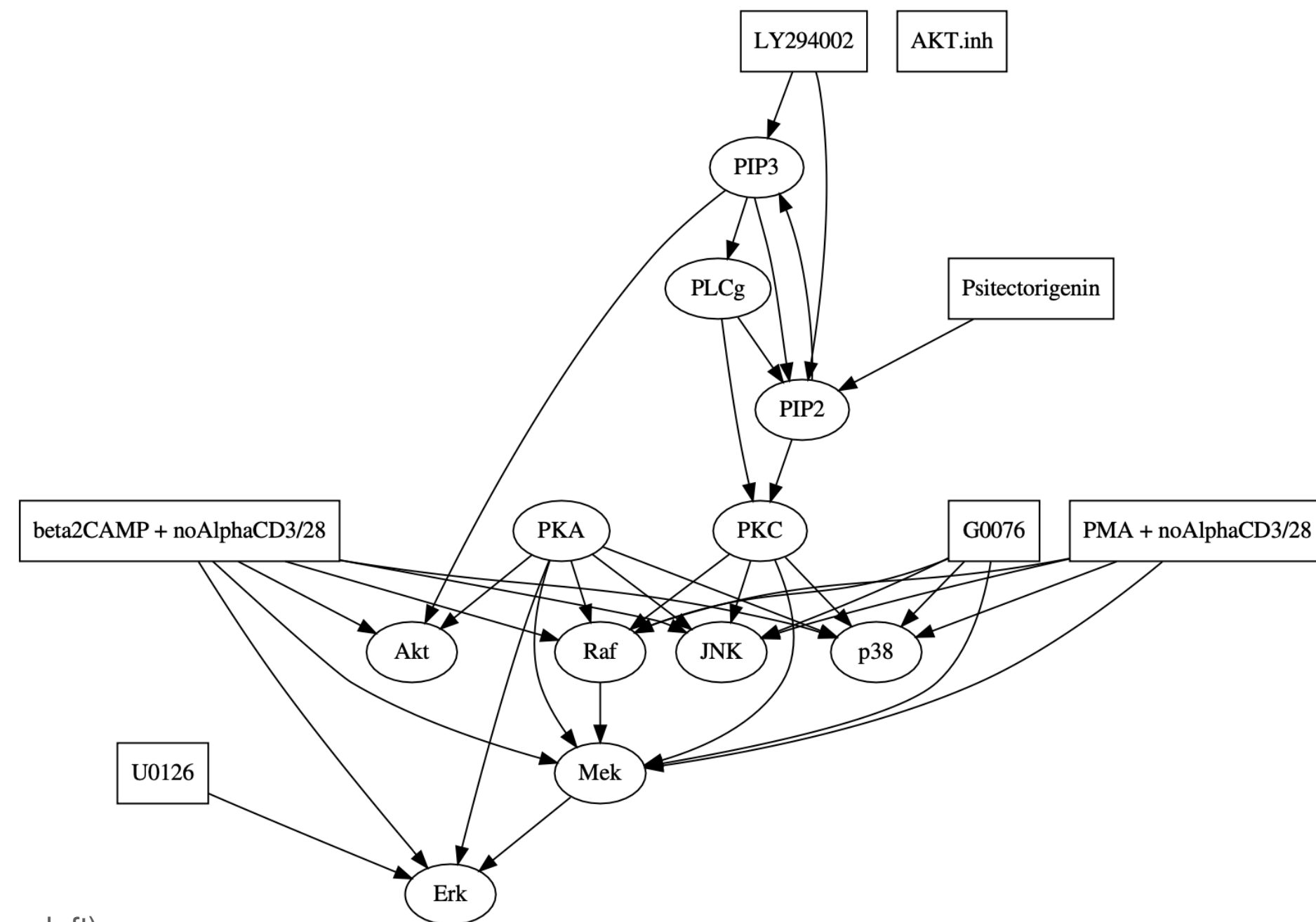
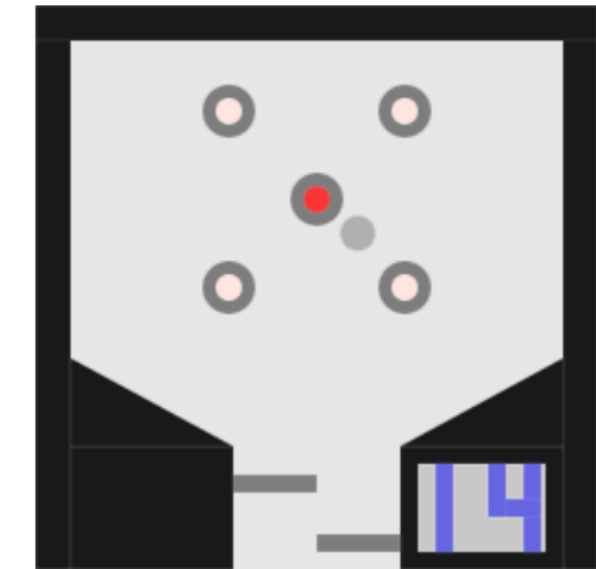
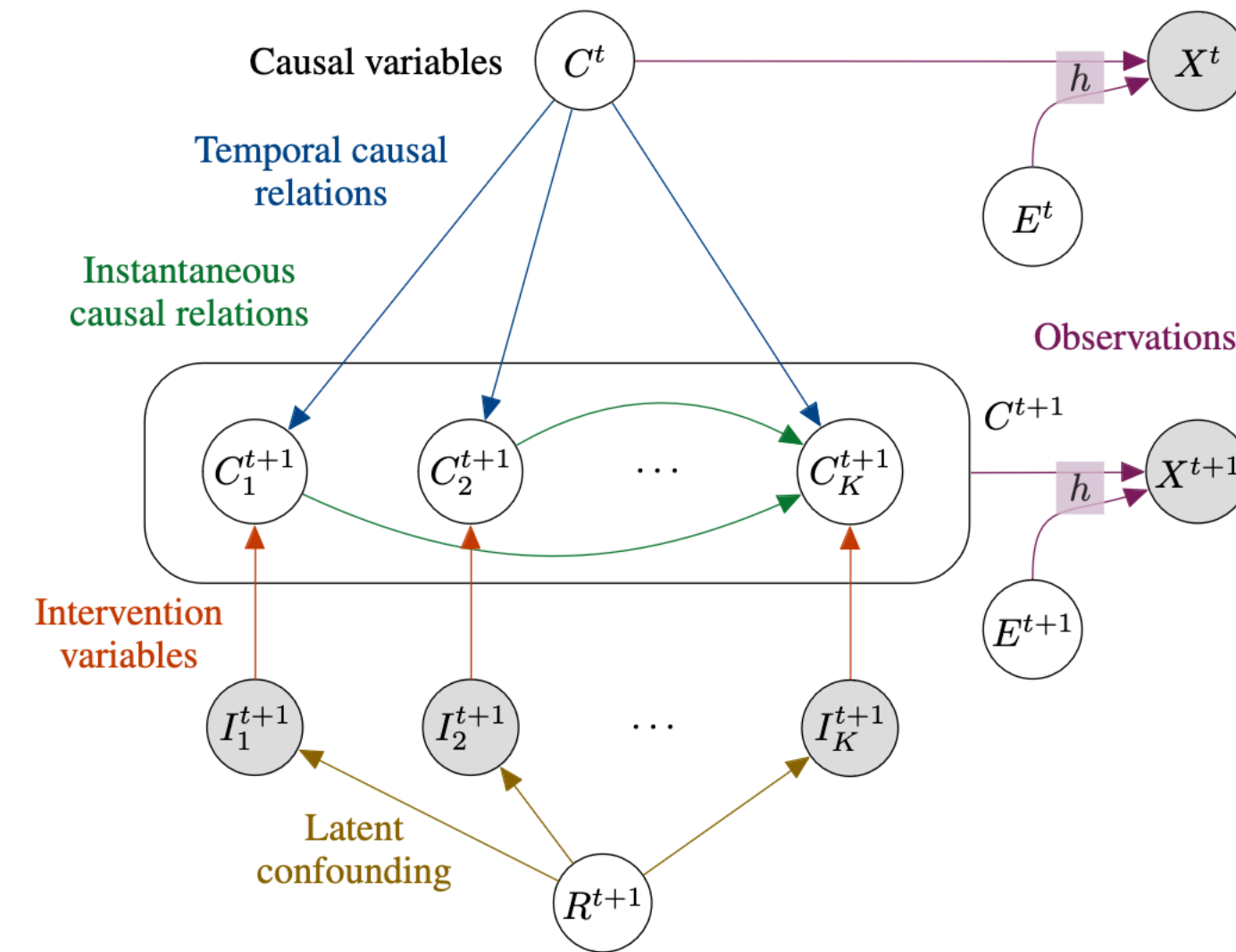
Causal effect of the CPAC on WPAC can be calculated given the optimal adjustment set





# Other Applications of Time Series Causal Discovery

- Gene knockout experiments
- Flow cytometry data
- Cohort studies in epidemiology
- Representation learning in robotics
- Financial markets



(Clockwise from bottom left)

Image: 'Causal protein-signaling networks derived from multiparameter single-cell data', Sachs et al, Science

Image: 'Do we Become Wiser With Time? On causal equivalence with tiered background knowledge', Bang et al, UAI 2023

Image: 'Causal Representation Learning for Instantaneous and Temporal Effects', Lippe et al, ICLR 2023

# Thank you!

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<https://climateinformatics-lab.com/about/>

